NUMERICAL METHOD FOR NON LOCAL **PROBLEM**

Reçu le 13/12/2007 - Accepté le 16/06/2008

Résumé

Dans ce travail on résout un problème parabolique avec des conditions aux limites non locales en utilisant la méthode des différences finis compactes d'ordre (d'ordre 6).la condition au limite intégrale est approchée la méthode de Simpson.les tests numériques montrent que la solution approchée coïncide avec la solution exacte sur plus de cinquante pour cent des points de discrétisation.

Mots clés: Schémas aux Différences Finis. Schémas Compactes d'ordre élevé, Problème non local, Ordre de convergence, Méthodes Numériques pour la résolution des équations aux dérivés partielles

Abstract

This paper is concerned with a high-order finite difference scheme for a non local boundary value problem of parabolic equation the integral in the boundary equation is approximated by the Simpson rule numerical experiments show that the approximate solution coincides with the exact one at more than fifty percent grid points discretization.

Keywords: Finite Difference Schemes, High-order Compact Schemes, Non local problem, Order of accuracy, Numerical methods for partial differential equations.

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ملخص

نقدم في هذا العمل حلا تقربييا لمعادلة تفاضلية ذات مشتقات جزئية بشروط حدّية غير محلّية مستعملين طريقة الفروق المنتهية المنضغطة من المرتبة السادسة . كما نقرب الشرط الحدّي التكاملي مستعملين طريقة " سمسون " . إنّ الاختبار إت العددية تبين أنّ الحلّ التقريبي المحصل عليه ينطبق على الحل الحقيقي في أكثر من خمسين بالمائة من نقاط التجزئة المقترحة

الكلمات المفتاحية: صيغ المنضغطة من مراتب عليا ، مسألة غير محلية ، مرتبة التقارب ، طرق عددية لحل المعادلات التفاضلة ذات المشتقات الحذئية

ntroduction

In this Paper we first introduce the compact sixth-order finite difference formula then we adjust compact finite difference formula for the following heat equation with non local boundary conditions.

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$$

$$(x,t) \in]0,1[\times]0,T[$$
(1)

$$u(x,0) = f(x)$$
 $0 < x < 1$ (2)

$$u_x(1,t) = g(t)$$
 $0 < t < T$ (3)

$$\int_{0}^{b} u(x,t)dx = m(t), \quad 0 < t < T$$
 (4)

where f, g, b and m are known.

points discretization.

J. Cannon and J. Vander Hoek [1] studied the existence and uniqueness proprieties of this problem. A.B. Gumel [2] has proposed numerical scheme of order $O(h_x^2 + h_t^2)$ L₀-stable parallel algorithm for soling this Problem later M. Akram and pasha [3] have proposed a more accurate Algorithm of order $O(h_x^3 + h_t^3)$. We propose a more accurate scheme of order $O(h_x^6 + h_t^6)$. The numerical experiments show that the sixth-order schemes are unconditionally stable and more accurate than that in [3] furthermore for the choice $h_x = \frac{1}{8}$ and $h_t = \frac{1}{1000}$. The approximate solution

2 SIXT-ORDER COMPACT FINITE DIFFERENCE FORMULA

coincides with the exact one at more than half of grid

Compact formula is a special finite difference method which uses the values of the function and its derivatives only at three consecutive points.

First keeping time continuous, we carry out a spatial discretization of $\frac{\partial^2 u}{\partial x^2}$, we divide the interval [0,1] using a uniform grid $0=x_0< x_1< x_2< ... < x_N$ with a mesh size $h_x=x_{i+1}-x_i$,

2.1 STANDARD COMPACT FINITE DIFFERENCE

The standard sixth-order compact finite difference formula for second derivative is:

$$\frac{h_x^2}{12} \left(U_{i-1}^{"}(t) + 10.U_{i}^{"}(t) + U_{i+1}^{"}(t) \right) = \tag{5}$$

$$U_{i-1}(t) - 2U_i(t) + U_{i+1}(t)$$

1. Write the compact finite difference formula in general form

$$h_x^2 \left(a_{-1} U_{i-1}^{"}(t) + a_0 U_{i}^{"}(t) + a_1 U_{i+1}^{"}(t) \right) = b_{-1} U_{i-1}(t) + b_0 U_{i}(t) + b_1 U_{i+1}(t)$$
(6)

where $a_{-1}, a_0, a_1, b_{-1}, b_0$ and b_1 are parameters to be determined.

2. Expand both sides of the equation (6) using Taylor series at the point x_i with respect to the discretization parameter h_x .

3. We obtain six equations by setting the coefficients h_x^j , j = 0,1,2,...,5 equal zero solve the six equations for the six unknown parameters the obtained accuracy is $O(h^6)$ for formula (6).

2.2- WRITE EQUATION (1) IN A DISCRET POINT FORM

$$\frac{\partial u(x_i,t)}{\partial t} = \frac{\partial^2 u(x_i,t)}{\partial x_i^2} \qquad i = 1, ..., N-1.$$
 (7)

Equation (5) is valid only for i = 2, ..., N-2 to attain the same accuracy at i = 1 and i = N-1 special formula must be developed.

When i = 1 we use the formula

$$\frac{h_x^2}{12} \left(14U_1^{"}(t) - 5U_2^{"}(t) + 4U_3^{"}(t) - U_4^{"}(t) \right) =$$

$$U_0(t) - 2U_1(t) + U_2(t)$$
(8)

From Simpson integration rule we have

$$\int_{0}^{b} u(x,t)dx \approx \frac{h_{x}}{3}(u_{0}(t) + 4u_{1}(t) + u_{2}(t)) = m(t),$$

b has been chosen as a grid point, and when i = N - 1 we use the formula

$$\frac{h_x^2}{12} \left(\frac{-127}{30} U_{N-4}^{"}(t) + \frac{86}{5} U_{N-3}^{"}(t) - U_{N-2}^{"}(t) + \frac{461}{15} U_{N-1}^{"}(t) \right) \tag{9}$$

$$=U_{N-2}(t)-U_{N-1}(t)+hU_{N}(t)$$

We use U to stand for the approximation value of u throughout this paper.

All Formula are $O(h_x^6)$ or written in matrix form

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$$AU''(t) = MU(t) + H,$$
 (10) where

$$A = \frac{h_x^2}{12} \begin{pmatrix} 14 & -5 & 4 & -1 & 0 \\ 1 & 10 & 1 & 0 & & & \\ 0 & 1 & 10 & 1 & 0 & & & \\ & 0 & 1 & 10 & 1 & 0 & & & \\ & & 0 & 1 & 10 & 1 & 0 & & & \\ & & 0 & 1 & 10 & 1 & 0 & & & \\ & & & 0 & 1 & 10 & 1 & 0 & & \\ & & & 0 & 1 & 10 & 1 & 0 & & \\ & & & & 0 & -\frac{127}{30} & \frac{86}{5} & -\frac{257}{10} & \frac{461}{15} \end{pmatrix}$$

$$H = \begin{pmatrix} \frac{3}{h_x} m(t) \\ 0 \\ \vdots \\ 0 \\ h_x U_M \end{pmatrix}$$

Finally we obtain

$$U''(t) = A^{-1}MU(t) + A^{-1}H$$
.

Putting $A^{-1}M = B$ and $A^{-1}H = R(t)$

$$U''(t) = BU(t) + R(t).$$
 (11)

Substituting in (7) we get a system of ordinary differential equations

$$\frac{dU(t)}{dt} = BU(t) + R(t), \qquad (12)$$

with the initial condition U(0) = f(x).

Putting

$$f(t,U(t)) = BU(t) + R(t),$$

we obtain the following equation

$$\frac{dU(t)}{dt} = f(t, U(t)). \tag{13}$$

We solve this equation using fourth-order Runge-Kutta Method

$$k_{1} = f(t_{0}, U_{0})$$

$$k_{2} = f(t_{0} + \frac{1}{2}h_{t}, \frac{k_{1}}{2}h_{t}U_{0})$$

$$k_{3} = f(t_{0} + \frac{1}{2}h_{t}, \frac{k_{2}}{2}h_{t}U_{0})$$

$$k_{4} = f(t_{0} + h_{t}, k_{3}h_{t} + U_{0})$$

$$U_{N+1} = U_N + \frac{1}{6}h_t(k_1 + 2k_2 + 2k_3 + k_4)$$
 (14)

3 COMPUTATIONAL RESULTS

In order to test the sixth-order compact finite difference scheme, we consider the Problem:

Consider the heat equation with

$$f(x) = 0.5x^2$$
$$g(t) = 1$$

$$m(t) = 0.75t + \frac{1}{6}(0.75)^3$$

which is easily seen to have exact solution

$$u(x,t) = 0.5x^2 + t.$$

Using Runge-Kutta method this problem is solved for

$$h_{x} = \frac{1}{8},$$

$$h_{t} = \frac{1}{1000};$$

$$h_{x} = \frac{1}{10},$$

$$h_{t} = \frac{1}{1000}.$$

For $h_x = \frac{1}{8}$, $h_t = \frac{1}{1000}$, the results of approximate solution are tabulated in table 1.

1	X	exact solution	approximate		
solutio	on 1/8	absolute error 8.8125x10 ⁻³	8.3865x10		
2		7.5053×10^{-2}			
	1/4	0.03225	2.8182×10^{-2}		
		4.068×10^{-3}			
	3/8	7.1313x10 ⁻²	7.1477x10		
2		1.64×10^{-4}			
	1/2	0.126	0.126		
		0			
	5/8	0.19631	0.19631		
		0			
	3/4	0.38381	0.38381		
		0			
	7/8	0.38381	0.38381		
		0			

Table 1

For $h_x = \frac{1}{8}$, $h_t = \frac{1}{1000}$, the results of approximate solution are tabulated in table 2.

	x	exact so		approximate
solution	1/10	absolute 0.006	e error	0.14449
	1/5	0.021	0.13849	
1.7083x10 ⁻²			$3.917x10^{-3}$	
$3/10$ 4.5849×10^{-2}		0.046	1.51x10 ⁻⁴	
1.0-2	2/5	0.81	0-5	8.10446
x10 ⁻²	1/2	4.46x1 0.126	0 '	0.126
	3/5	0.181	0	0.181
			0	
	7/10	0.246	0	0.246
	4/5	0.321	0	0.321
	9/10	0.406	•	0.406
			0	

Table 2

CONCLUSION

It is observed that the results obtained using compact sixth-order finite difference scheme are highly accurate. As compared to those of [3] and the method developed is sixth-order accurate in space and fourth-order in

Time with very high speed fourth-order Runge-Kutta algorithm it is to be noted that only one iterate was needed to obtain the results shown in both table 1 and 2.

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