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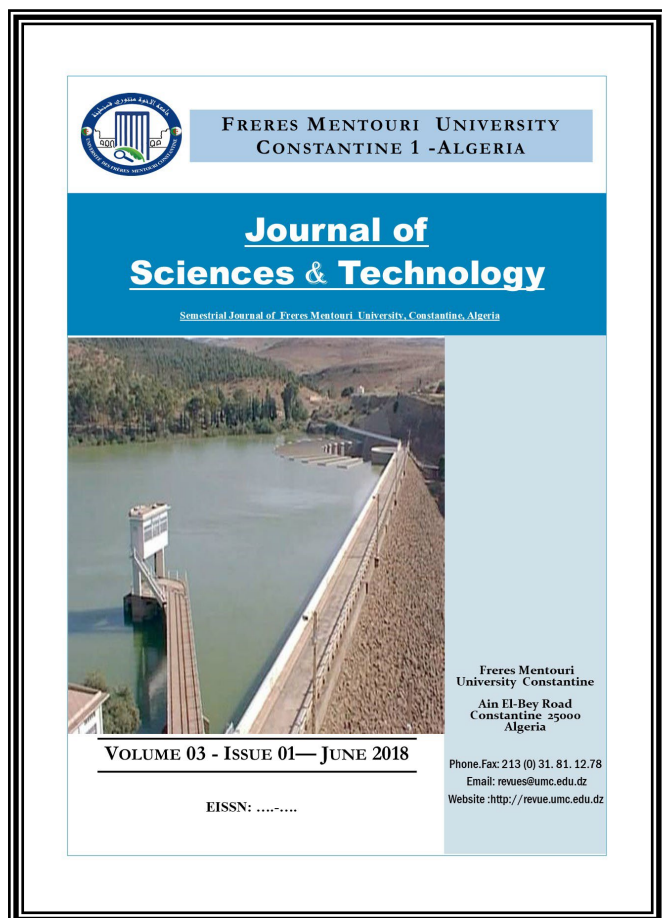
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SUMMARY

S
U
M
M
A
R
Y

7

METHYLENE BLUE MINERALISATION BY ELECTROCHEMICAL PROCESS MEDIATED BY COBALT CATALYST ON PLATINUM ELECTRODES.

O BRAHMIA, F LOUAFI

13

THE EFFECT OF THE THERMAL INERTIA ON THE TEMPERATURE OF A HEATING SLAB.

D ABBAZ, A CHAKER

17

3D NUMERICAL STUDY OF FLOW IN A SOLAR CHIMNEY POWER PLANT SYSTEM.

T TAYEBI, M DJEZZAR, H GOUIDMI

23

NUMERICAL STUDY OF THE MIXED CONVECTION HEAT TRANSFER IN ANNULUS HEATED BY JOULEAN EFFECT.

S TOUAHRI, T BOUFENDI

29

MINERALOGICAL CHARACTERIZATION OF SANDSTONE AND CLAY, NORTH-EAST CONSTANTINE.

M BENYAMINA, L CHETIBI, M BOUCHEAR

METHYLENE BLUE MINERALISATION BY ELECTROCHEMICAL PROCESS MEDIATED BY COBALT CATALYST ON PLATINUM ELECTRODES

Submitted on 08/07/2015 – Accepted on 27/12/2015

Abstract

In this study, the electrochemical decolorization of the Methylene Blue dye on Platinum electrodes was assessed. Direct oxidation results demonstrate a partial pollutant degradation reaching a maximum of 64 %. However, the addition of a small amount of a redox mediator $\text{Co}^{2+}/\text{Co}^{3+}$ is efficiently able to electrocatalyse the Methylene blue oxidation by shortening significantly the treatment time and enhancing clearly the dye decolorization rate. Nearly complete decolorization was achieved (92 % in 1h 45min). The most striking results achieved within the cyclic voltammetry study demonstrate undoubtedly the pollutant mineralisation. Electrochemical experiments were performed using the spectrophotometric method, which is very convenient, easy and allows monitoring the spectral changes as well as the determination of the dye concentration during the process. The kinetics data show a first-order indirect oxidation kinetics. A mechanism was proposed to explain the different phenomenon during the electrochemical process.

Keywords: Decolorization, Methylene Blue, catalyst, Platinum electrode, mineralisation.

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INTRODUCTION :

Methylene Blue (MB) is widely used in biology and chemistry for diverse applications such as; photosensitizer to generate Singlet oxygen, stain for fixed and living tissues, antidote to cyanide and nitrate poisoning (Parry, 1993). In food industry, it is used as optical oxygen sensors. Moreover, it's an organic dye, used to dye cotton, acrylic, silk and wood (*El hajj hassan and El jamal, 2012*). Generally, dyes are used in various industries such as textile, paint, leather, paper and food (*Hameed and Lee, 2009*). In the case of textile industry, up to 50 % of the synthetic dyes with different structural varieties such as; azo, diazo, quinine imine, thiazole and others (*Banat and Nigam, 1996*) are lost after the dyeing process and disposal out in the effluents (*Zollinger, 1991*). Therefore, their elimination from wastewaters is an obligation to prevent the ecosystem destruction. Conventional wastewater treatment based on biological process is not suitably enough to remove recalcitrant dyes from effluents (*Shaul et al., 1991*). Physical and chemical methods used for eliminating dyes (i.e. adsorption, incineration, electrocoagulation, photocatalysis, ozonation and others) are reasonably effective but relatively cost (*Zhu et al., 2000; Szyrkowicz et al., 2001*). That's why; it's necessary to find an effective wastewater method capable of degrading toxic organic compounds from industrial effluents. As alternative, the electrochemical oxidation process is a clean advanced oxidation technology because, the main reagent; the electron, is a clean one (*Jüttner et al., 2000*). It was applied successfully and proved to be convenient and fruitful to destruct bio-refractory organic compounds due to its high effectiveness and environment well-suited. In the electrochemical oxidation under room temperature and atmospheric pressure, generally, researchers focus their particular interest on the anode oxidation process than the

cathode reduction. The Electrochemical methods designed for wastewater treatment consist of direct and indirect oxidation. Mediated Electrochemical Oxidation (MEO) with a redox mediator is considered as one alternative to efficiently remove color from solutions of structurally different dyes. It is as well admitted through this indirect oxidation that a strong oxidative intermediates were generated in situ and consequently convert pollutants into less hazardous products (*Sanromán et al., 2004*). In this context, we accomplish the MB electrochemical degradation in the presence of $\text{Co}^{2+}/\text{Co}^{3+}$ selected as a redox mediator using Pt electrodes. Moreover, it is important to note the conductor behavior of MB, that's why, we achieved this study without any supporting electrolyte to test the feasibility of the MB electrochemical degradation. It should be noted as well that generally dyes are susceptible to undergo a photochemical degradation as they absorb in the visible part of the electromagnetic spectrum, that's why we have worked in the obscurity to avoid any probability of a possible photodegradation pathway. The aim of this work was to test the feasibility of the electrodegradation of MB in our particular conditions. The decolorization rate has been evaluated with and without the redox mediator and the mechanism of the process was suggested in both direct and indirect oxidation.

2. EXPERIMENTAL SECTION

2.1 Materials

Methylene blue (MB) was purchased from Labosi (for analysis) and used without further purification. The cobalt chloride ($\text{CoCl}_2 \cdot 6 \text{H}_2\text{O}$) used as redox mediator was purchased from Biochem. Solutions were prepared using distilled water.

2.2 Methods summary :

The electrochemical process was carried out using the spectrophotometric method to follow the dye decolorization. The study was conducted on aqueous solution of MB (3.125 μM), initial pH of 7.8, under atmospheric pressure, at room temperature and in the dark. Experiments were carried out in an electrochemical cell containing the amount of 25 ml of MB for each experiment and using electrodes placed in the cell centre with a distance of 2 cm separating them. The anode and cathode are Pt wire from Voltalab. The ratio electrode surface/volume of dye solution was 0.04 $\text{m}^2 \cdot \text{m}^{-3}$ at laboratory scale. A constant voltage drop of 2 Volt was applied to the electrodes using Potentiostat (Alimentatore per elettroforsi el VI 16, Italy). The reaction vessel was placed on a magnetic stirrer for continuous stirring to ensure the solution homogeneity during the electrochemical process. The conductivity of the initial MB solution was equal to 14.5 $\mu\text{S}/\text{cm}$ measured by a conduct-meter model (Inolab Cond 7110). According to this conductor behavior, we choose to perform our experiments without any electrolytes to test the feasibility of the MB degradation in this condition. During the electrochemical process, after each treatment time, we transfer the solution to the UV-visible spectrophotometer (Jenway 6505) to record the absorption spectra of the dye solution and to measure the absorbance at the maximum of MB absorbance (660 nm) using a matched pair of quartz flows cells (1 cm path length). The absorbance data were converted to the concentration using Beer-Lambert (Eq.1). $A = \epsilon \cdot C \cdot L$ (1), where A and ϵ are respectively the absorbance and molar absorptivity coefficient values at 660 nm, C is the dye concentration at time t , l is the light path length. The value of ϵ at 660 nm is deduced from the MB calibration curve, it is equal to 38701 $\text{M}^{-1} \cdot \text{cm}^{-1}$. The assays were done twice; the experimental error was below 3 %. The decolorization rate of the dye (Dec %) was expressed as a percentage and calculated by the following (Eq.2). % dye decolorization = $[(C_0 - C_t) / C_0] \times 100$ (2), where C_0 and C_t are the dye concentrations at time 0 and time t respectively. The concentration of the dye was calculated from the absorbance value at 660 nm using a calibration curve. Voltammetric experiments were carried out with a potentiostat model Gamry (USA). The working electrode was a platinum electrode and a reference electrode was a saturated calomel electrode (SCE). All potentials were reported vs. the SCE. A platinum electrode was used as the counter electrode. The scan rate was 100 mV/s . The experiments were achieved using a cell of 20 ml, we purged the dissolved oxygen by nitrogen bubbling during 25 minutes and we used as 0.1 M of KCl as supporting electrolyte.

3. RESULTS AND DISCUSSION

3.1 Direct oxidation of methylene blue MB

3.1.1 Decolorization rate

To assess the feasibility of the electrochemical process conducted on a solution of methylene blue (3.125 μM) at initial pH of 7.8, we experimentally followed the decolorization by measuring the dye absorbance at its

maximum absorption (660 nm) as a function of the different electrochemical treatment time. The decolorization expressed in terms of percentage was calculated according to (Eq.1). The obtained results are shown in (Fig.1). It should be noted that no significant change was observed on the initial pH value of MB during the electrochemical process.

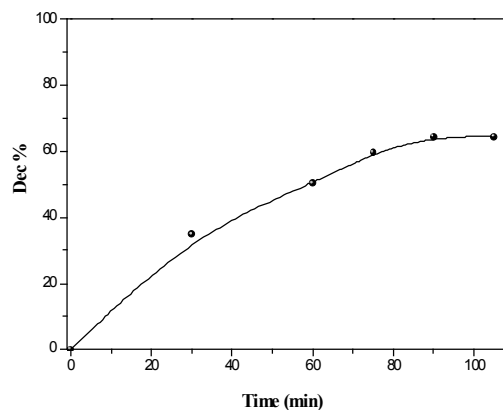


Fig.1. MB decolorization percentage (Dec %) versus the treatment time

Figure.1 indicates a progressive increase of the dye decolorization up to 90 minutes where this last reached a maximum of 64 %. Experiment reveals the gradual disappearance of the blue color which suggests the oxidation of the dye; furthermore, the reaction by-products are colorless. For a treatment time of 105 minutes, the decolorization percentage doesn't change; this leads us thinking about an inhibitory effect against the MB elimination.

3.1.2 Electro-degradation kinetics

To better understand the pollutant behavior, we converted the absorbance to the corresponding concentration and then plotted the pollutant disappearance kinetics (Fig.2).

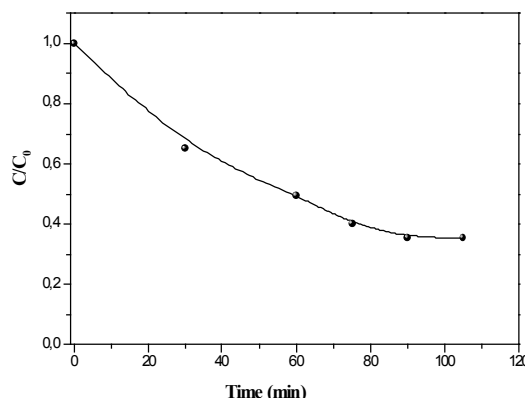
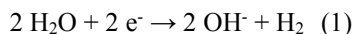


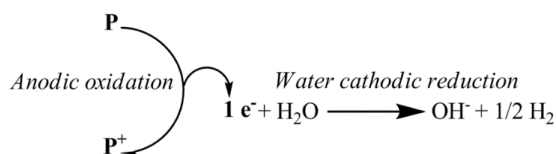
Fig.2. Electrochemical decolorization of Methylene blue (direct oxidation)

According to the plotted curve, it appears two different phases, the first one correspond to a treatment time between 0 and 90 minutes, the elimination rate is rapid at the beginning of the reaction ($0,043 \mu\text{mol} \cdot \text{l}^{-1} \cdot \text{min}^{-1}$) and the

half-life time is 60 minutes. During this time period, we can readily admit that the reaction proceeds most probably by a transfer of electrons. In other words, the pollutant undergoes anodic oxidation from one hand, since it is capable to give electrons, especially those of the lone doublets of sulfur and nitrogen atoms. On the other hand, we admit a cathodic reduction of water; this last lead to the formation of OH⁻ anions with the release of H₂ according to the (reaction.1)



We can summarize the proposed mechanism of electro-degradation according to (scheme.1) (where P and P⁺ are respectively the pollutant and the oxidized pollutant).



Scheme.1. MB direct oxidation mechanism

The second part of the curve is included between 90 and 105 minutes, we stopped at this end, because the electro-degradation rate no longer changes. This strongly suggests that the intermediates formed during the reaction can compete with the pollutant itself and thus inhibit its elimination. We can generally accept that reactions consuming electrons can limit the MB direct oxidation in solution. All this goes to prove that the direct electrochemical oxidation is only capable to partially oxidize the MB solution, that's why it's interesting to optimize this process to reach the dye total degradation.

3.2 Indirect oxidation :

It's well established that the redox mediators such as (Fe^{2+/3+}, Ce^{3+/4+}, Co^{2+/3+}) are able to generate electrochemically oxidizing species capable of inducing degradation of dyes (Bringman et al., 1995; Farmer et al., 1992). Therefore, it is interesting to consider the redox catalyst effect on MB oxidation. We started our experiment with Ce^{3+/4+} catalyst, no significant change was observed in terms of dye disappearance, this is probably due to its moderate oxidation potential (1.72 V). The second attempt was performed using the couple Co^{2+/3+} with a slightly higher oxidation potential (1.92 V). We tested its effect on MB electro-degradation.

3.2.1 Evolution of MB absorption spectra :

In terms of experimental conditions, the study was performed by adding a solution of CoCl₂ (10⁻⁷ M) to the initial MB solution (3.125 μM), (initial pH 7.8) using the same platinum electrodes. The monitoring of the absorption spectra evolution according to the treatment time between 0 and 105 minutes was accomplished using UV-visible spectrophotometric method. According to (Fig.3), we presented those recorded after 30 and 60 minutes. It clearly appears a decrease in the absorbance at MB maximum absorption (660 nm) in the visible region between (550-750 nm).

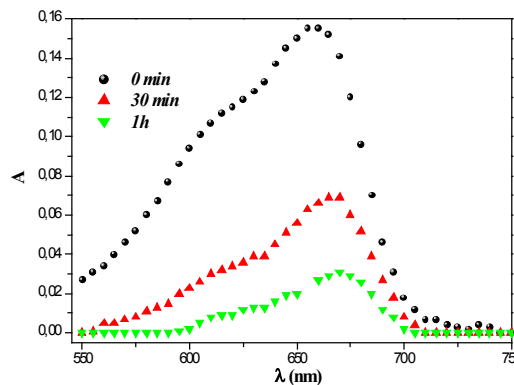


Fig.3. Evolution of the MB absorption spectra during the indirect oxidation

Figure 4 shows properly according to the treatment time, the evolution of the absorbance (A) at 660 nm, which reflects the effective disappearance of the dye and thus our process was significantly optimized by just adding a small quantity of a catalyst.

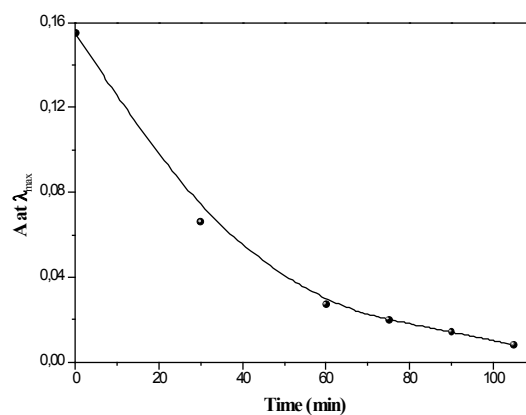


Fig.4. Absorbance evolution (at 660 nm) according to the treatment time

3.2.2 Decolorization rate :

Figure 5 shows the MB decolorization percentage according to the different treatment time during the indirect oxidation.

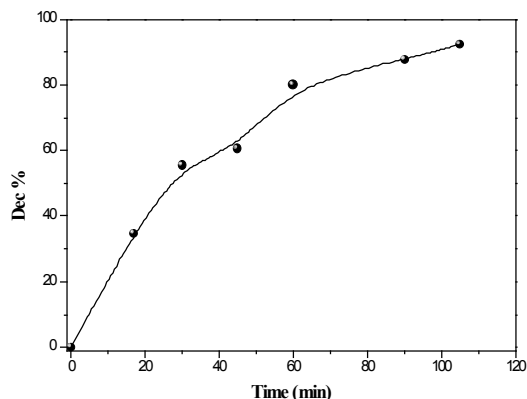


Fig.5. Methylene blue decolorization rate (Dec %) in the presence of Cobalt catalyst

The most important result shows a nearly complete decolorization of 92 % after 105 minutes against 64 % within the direct oxidation. *This reflects the substantial role played by the catalyst in the electrochemical process to increase the dye decolorization percentage.*

3.2.3 Electro-degradation kinetics :

To illustrate the catalyst effect within the indirect oxidation, we have calculated the concentrations from their corresponding absorbances and plotted the kinetics of MB disappearance (C/C_0 versus the treatment time t). (Fig.6)

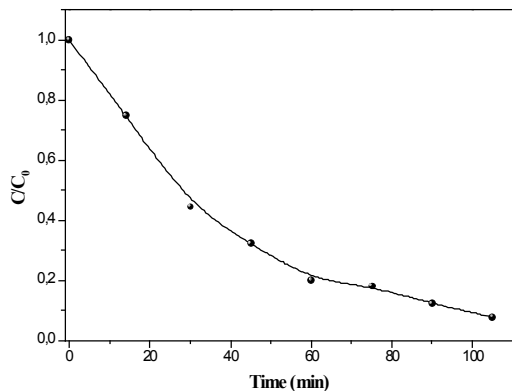


Fig.6. Methylene blue electrochemical decolorization (indirect oxidation)

Figure.6 shows explicitly the dye fast indirect oxidation, the initial rate of disappearance equal to ($0.07 \mu\text{mol.l}^{-1}\text{.min}^{-1}$) is 1.62 times faster than the one of the direct oxidation. The half life time is only 28 minutes against 60 minutes in direct oxidation. In other words, the process with the cobalt redox mediator is able to electrocatalyse efficiently the oxidation of MB shortening significantly the treatment time. The superposition of the curves (with and without catalyst) clearly shows these finding (Fig.7).

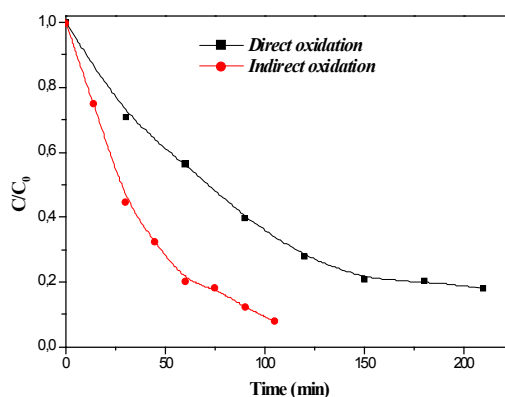


Fig.7. Comparison between the two MB disappearance kinetics (with and without catalyst).

These results demonstrate that the addition of a small amount of cobalt (10^{-7} M) is largely enough to effectively catalyze the MB electrochemical reaction. Furthermore, in terms of reaction kinetics, the indirect oxidation is a first order kinetics. The reaction rate constant is deduced from the curve representing ($\ln C_0/C$ versus time) (Fig.8). The plot is linear ($R^2 = 0.995$) and the rate constant value k is 0.024 min^{-1} .

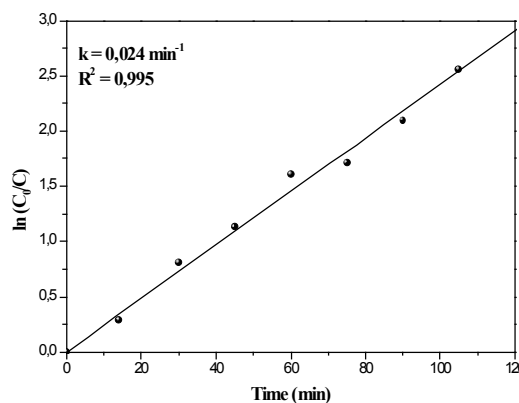
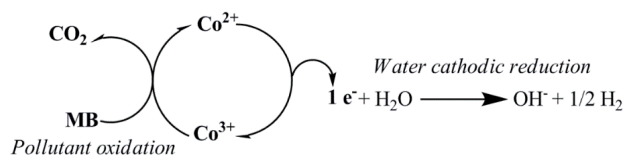


Fig.8. Determination of the rate constant of the MB indirect oxidation.

In this process, metal ions are oxidized anodically from a stable oxidation state to reactive species, which in turn, are capable of oxidizing organic substances to CO_2 (Bringmann et al., 1995). The electro-degradation mechanism is proposed by scheme.2.



Scheme.2. MB indirect oxidation mechanism

3.2 Cyclic voltammetry :

The cyclic voltammograms (CV) of methylene blue at the potential range -0.8 V to 0.2 V are shown in (Fig.9). The curve (a) on the graph present free MB which yielded one reversible redox system, with the anodic peak potential (E_{ap}) at -0,148 V, the cathodic peak potential (E_{cp}) at -0,328 and the peak separation $\Delta E_p = 1.8$ V. In the indirect oxidation, we reached 92 % of MB degradation after 1h 45 min. To guarantee a total MB degradation, we electrochemically treated the solution longer (2h 15 min). The (CV) of this solution was presented on the curve (b). Several conclusions can be deduced; first of all, it appears clearly the complete disappearance of the reversible system found with Free MB; in other words, a complete degradation of the product was observed. Added to this, after a precise search for the apparition of any anodic or cathodic peak, no one was found in the potential range [-2 V, +2 V]. These results provide evidence that all the products yielded from the MB transformation were degraded in their turn. With harmony to these results, we can confirm the mineralisation of the MB dye according to the following reaction: $MB (+ e^-) \rightarrow CO_2 + H_2O$. We searched the reduction peak of CO_2 situated at -2.15 V/CSE according to the following reaction: $CO_2 + e^- \rightarrow CO_2^{\cdot-}$. This peak disappears in our conditions most likely because of the nitrogen bubbling in the solution during all the experiment.

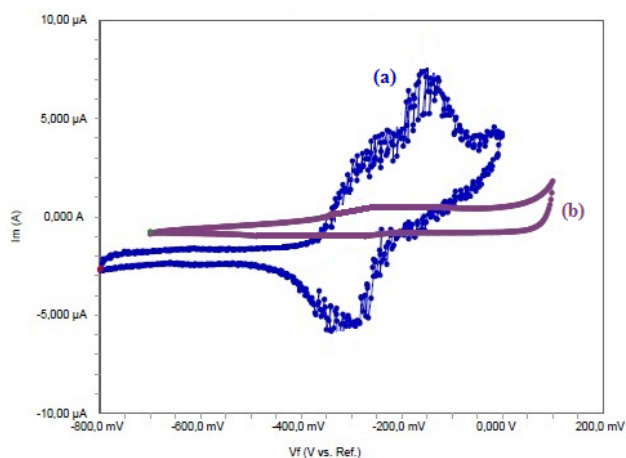


Fig.9. Methylene blue Cyclic Voltammograms, (a): free MB, (b): MB with cobalt catalyst

CONCLUSION

The spectrophotometric method was applied successfully on the decolorization of Methylene Blue from aqueous solution by electrochemical process. The results confirm the ability of the direct oxidation to partially oxidize the Methylene blue pollutant. However, a mineralization of the pollutant was obtained by adding a small amount of cobalt redox mediator which increases the decolorization rate and shortens the treatment time. It is noteworthy that the absence of a supporting electrolyte in this study didn't affect the efficiency of the electrochemical process. Added to this, cobalt is not consumed during the process, that's why it can be recovered from the effluent by precipitation

or ionic exchange avoiding thus its discharge in the environment.

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THE EFFECT OF THE THERMAL INERTIA ON THE TEMPERATURE OF A HEATING SLAB.

Submitted on 18/12/2013 – Accepted on 24/08/2014

Abstract

The paper presents the influence of the thermal inertia on the temperature of a heated concrete slab. This is a solar sensor provides a solar heating system floor, which the energy input.

The concept of thermal inertia is not easy to grasp. It is defined as the speed that helps a system ((building in our case) reacts to the change in operating conditions. The response of the building facing to the stresses is largely depending on the thermal properties of constituent materials. This feature is related to good performance, good use, and comfort of the thermal machine which is called ‘‘habitat’’.

The objective of this work aims to study the influence of the inertia on the surface temperature of the floor, to design the future of homes with high inertia and very low energy consumption with satisfactory comfort conditions.

Keywords: thermal inertia, solar heating, solar collector, floor, Forte inertia habitat.

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Algeria.

I. INTRODUCTION:

Today, the construction industry goes into a new era. The energy consumption of buildings representing Algeria, almost 47% of the energy produced and they are responsible for over 25% of greenhouse gas emissions must be reduced by economic and energy solutions respect to the environment.

For this, improving the building’s envelope which is reinforced by insulation and better treatment of thermal bridges which introduce lower thermal requirements in air conditioning and heating should be taken into consideration. Further research should focus on efficient building heating systems to control the atmosphere of living with a lower energy cost. Certainly, maintaining the atmosphere is entrusted to the heating system whose quality depends greatly on the design, the design and implementation of the facility. At the same time, technological development in the field of current heating needs to go parallel to the direction of reducing the negative environmental impact through the use of renewable energy sources and to ensure also the security of our energy supplies facing the depletion of fossil energy resources.

In this approach, the heated floor has a particular place in technology. It provides optimal heat distribution vertically and horizontally, perfectly compatible with renewable energy sources. It is one of low temperature systems which reduces the energy consumption through its use.

Research has been undertaken on this heating technology and several designs were studied. A. Mokhtari et al (1992) demonstrated in a theoretical and experimental study of a storage room with a direct solar floor a capture ratio of 8 to 10% is more than enough according to the Algerian climate. The authors also noted that a sensor surface equal to 10% of the heating floor’s surface can be used without fear of overheating [1].

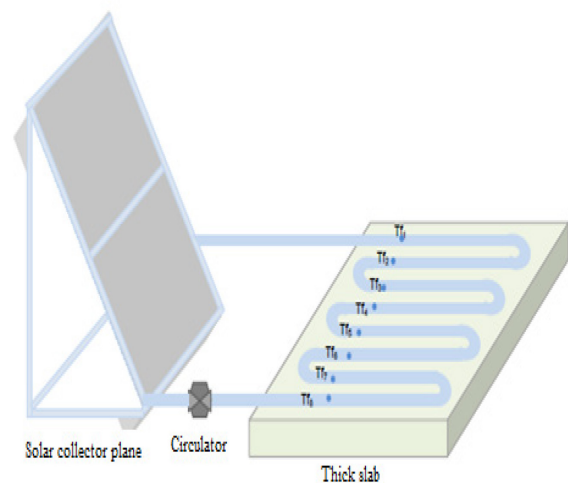
For the dimensions that are suitable for our climate, and to avoid the overheating phenomenon and have some thermal comfort. Kharchi A. (2000), used a report in his experimental

study, capture area / exchange area (slab) equal to 0.5, for a slab thickness of 10 cm above the grid [2].

II. THE HEATING SYSTEM

A direct solar floor consists essentially of three elements:

- The solar panel captures that convert transforms sunlight into heat.
- A slab wherein in which the heat transfer fluid heated by the sensors. The latter simultaneously serves to store the heat generated by the sensors and to return in the same way as a conventional low-temperature floor heating, but with a certain time lag.
- A transfer group that manages the heating of the PSD [3].



III. MATHEMATICAL FORMULATION SYSTEM

The system is modeled according to nodal method, based on the heat balances of each element which constitutes the heating system: sensor, coolant, floor consisting of a concrete slab.

A. Simplifying assumptions

- The physical properties of materials are assumed to be constant.
- The flow regime is transitional.
- The different solid media have a uniform temperature in a plane normal to the direction of flow.
- The heat flows are of one-dimension.
- The heat transfer fluid used is a pure water.
- The heat losses between the solar collector and the floor are negligible.
- The temperature of the water leaving the solar collector is equal to that of the water at the inlet of the under floor heating.
- We limit ourselves only to study the exchange of heat from the top of the coil (the floor is well isolated from the ground side).
- The heat transfer fluid circulates on the velocity u in the tube.
- The floor temperature is considered uniform.

B. Heat balance

1) Useful power recovered by the fluid

The useful power recovered by the heat transfer fluid is governed by the equation [4], [5]:

$$P_u = F_R \cdot ((\tau\alpha)_{eff} \cdot P_g - U_g \cdot (T_{fe} - T_a)) \cdot S_c \quad (1)$$

Or :

- $(\tau\alpha)_{eff}$: Effective coefficient of absorption.
- F_R : Overall efficiency of the thermal exchange of the sensor.
- T_{fe} : Entered temperature of the coolant.
- P_g : Overall power.
- U_g : overall heat loss.

2) Heat balance at the hot slab

By performing a heat balance at each node, we obtain a system of two equations describing the behavior of the floor.

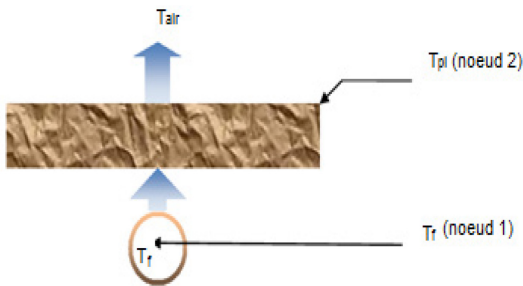


Fig.2. Nœuds considered in the floor

- Nœud 1 : (the heat transfer fluid)

$$\begin{aligned} M_f C_{p_f} \frac{\partial T_f}{\partial t} + U_f C_{p_f} \frac{\partial T_f}{\partial y} \\ = h_{vplf} S_{plf} (T_{pl} - T_f) \\ + h_{cplf} S_{pl} (T_{pl} - T_f) \end{aligned} \quad (2)$$

Dividing by $M_f C_{p_f}$, we obtain:

$$\begin{aligned} \frac{\partial T_f}{\partial t} + \frac{V_f V_{fmax}}{M_f} \frac{\partial T_f}{\partial y} = \frac{h_{vplf} S_{plf}}{M_f C_{p_f}} (T_{pl} - T_f) \\ + \frac{h_{cplf} S_{pl}}{M_f C_{p_f}} (T_{pl} - T_f) \end{aligned} \quad (3)$$

- Nœud 2: (the floor)

$$\begin{aligned} \frac{dT_{pl}}{dt} \\ = \frac{h_{vplf} S_{plf}}{M_{pl} C_{p_{pl}}} (T_f - T_{pl}) \\ - \frac{S_{pl}}{M_{pl} C_{p_{pl}}} (\varphi_{vpla} + \varphi_{rpl}) \end{aligned} \quad (4)$$

With:

φ_{rpl} : Exchangeradiantwith air.

φ_{vpla} : Exchangeconvectionwith air.

This equation completed by the initial conditions and system boundary, forms a system of nonlinear equations and coupled. The resolution is performed by the finite difference method using the descending implicit scheme for the convective term fluid and an explicit scheme for the transient term.

IV. RESULTS AND DISCUSSION

The thermal inertia imposes a certain time delay between the moment when the water is introduced into the tube and the temperature of the surface varies.

The thermal inertia associated with conduction's phenomenon depends on the thickness of the slab and the thermo physical characteristics of the materials which consist of (volume, mass thermal conductivity, thermal emissivity) [2].

A. Temporal variation in useful power of the sensor

It is evident that the useful power recovered by the fluid closely depends on the global solar radiation. Thus, and as shown in Figure 3, the useful power (heat supplied to the floor) has a bell shape, it is between 120 and 300 watts.

This result has a good agreement with what was found in the literature [2].

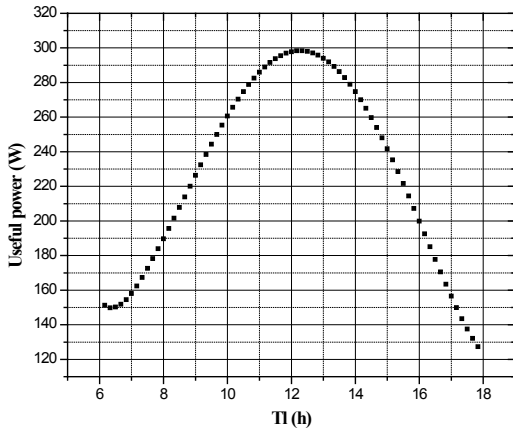


Fig .3. Variation temporal of the useful power of the sensor

B. Assessment of the role of inertia on the floor temperature:

1) Influence of the thickness of the concrete:

a)-Effect of the thickness of the concrete on the floor temperature:

Figure 4.a illustrates the evolution of the floor's maximum temperature as a function of time for different thicknesses of the concrete's layer. It is clear that the maximum temperature of the floor decreases when the thickness of the layer of concrete increases.

The floor temperature will be even weaker than the concrete mass is important.

b) Effect of the thickness of the concrete over the useful power:

In Figure 4.b we can find that the consumption of useful power decreases when the thickness of the upper concrete layer is increased (the thermal losses between the sensor and the slab being assumed negligible, the heat transferred to the slab is thus equal to the energy captured by the "power output" sensor).

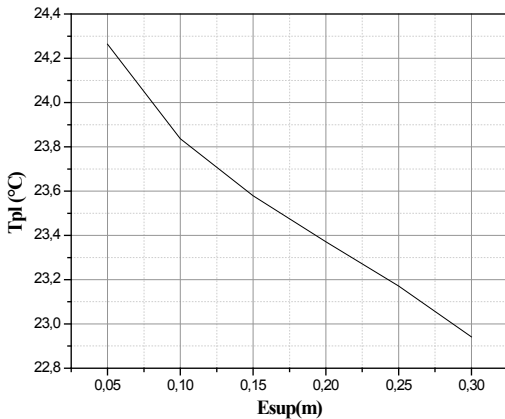


Fig .4 .(a) Influence of the thickness of the concrete on the floor temperature.

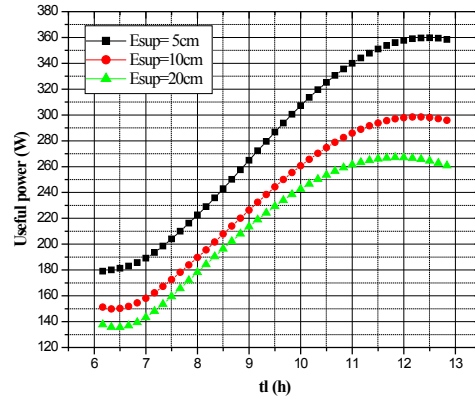


Fig .4.(b) Effect of the thickness of the top layer of the useful power .

2) Influence of the thermal resistance of concrete

It is evident that the floor's temperature is highly dependent on the thermal resistance of the top layer of concrete. Thus, and as seen in Figure 5, the increasing of the thermal resistance of concrete leads to a lower of the heat exchange with the atmosphere which directs to a reduction of the floor temperature.

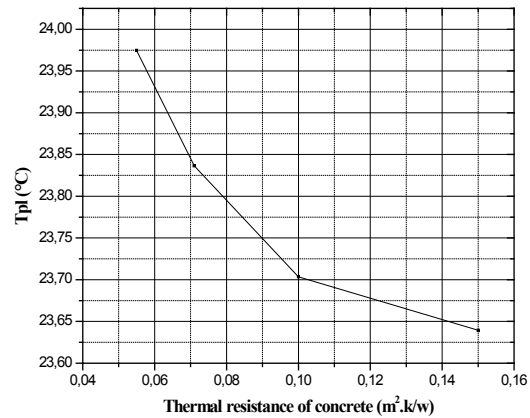


Fig .5. Evolution of the floor temperature in function of the thermal resistance of the top layer of concrete

3) Influence of emissivity of concrete

The examination of the curves in Figure 6 allows saying that the floor temperature is more important in the case where the radiation is not taken into consideration; in this case the amount of heat transferred to the air will be considerably larger.

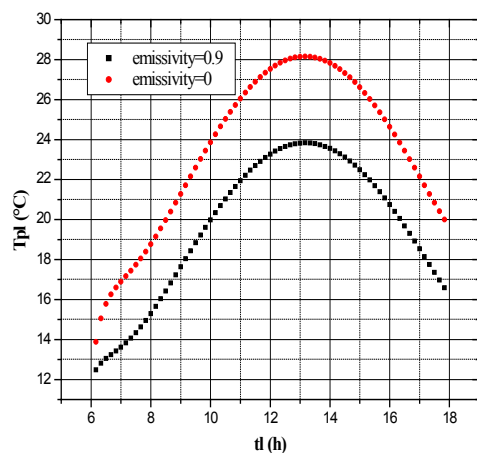


Fig .6. Temporal evolution of the temperature of a radiant floor and a non-radiant floor

CONCLUSION

Thermal inertia is thus a complex phenomenon. Multiple criteria should be taken into account to obtain the same comfort for less consumption.

The result of the study conducted the following conclusions:

The inertia of the floor is directly related to the thickness of the concrete layer located above heating pipes. With this configuration, it has been shown that the floor temperature was even lower than the concrete mass increased.

Therefore, it is recommended to increase as much as possible the thickness of the top layer of concrete. Nevertheless, we cannot afford to have too thick floor. Indeed, the "National Building Code" sets the minimum thickness of concrete floors of homes to 75 mm for the slab itself, and the use of a greater thickness is not necessary. A slab 10 cm thick may be a compromise quite interesting.

Furthermore, the nature of the floor covering affects the thermal power emitted by the floor and its surface temperature.

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3D NUMERICAL STUDY OF FLOW IN A SOLAR CHIMNEY POWER PLANT SYSTEM

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Abstract

Heat transfer process and fluid flow in a Solar Chimney Power Plant System (SCPPS) are investigated numerically. As simulation object we use the Spanish prototype plant. The calculative model and boundary conditions in calculation are introduced. Boussinesq model was chosen in the natural convection processus, Discrete Ordinate radiation model was employed for radiation. The principal factors that influence on the performance of the Solar Chimney have been analysed. The effects on the flow of the Solar Chimney which caused by solar radiation intensity have been simulated. The calculated results are compared and are approximately equivalent to the relative experimental data of the Manzanares prototype. It can be concluded that the temperature difference between the inlet and outlet of collector, as well as the air velocity in the collector of the system, is increase with the increase of solar radiation intensity and the pressure throughout system is negative value.

Keywords: Terms—Solarchimney power plant, Numerical simulation, solar radiation intensity, Flow characteristics.

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I. INTRODUCTION

The Solar Chimney Power Plant System (SCPPS) is a natural driving power generating system. It can convert solar energy first into thermal energy then into kinetic energy finally into electrical power. The concept was first suggested by Günther in 1931 and again by Schlaich [1] in 1978. Subsequently a prototype of a solar chimney with a height of 194.6m and collector area of radius 122 m was constructed at Manzanares, (Spain) and data of actual working of the solar chimney was collected [1]. Schlaich reported the nominal electric power output at Manzanares to be 50 KW.

As the solar chimney, power plant systems could make significant contributions to the energy supplies of those countries where there is plenty of desert land, which is not being utilized, and sunlight available in Africa, Asia and Oceania, researchers have made many reports on this technology in the recent few decades.

Haaf et al. [2] provided fundamental investigations for the Spanish prototype system in which the energy balance, design criteria, and cost analysis were discussed. The next year, the same authors reported preliminary test results of the solar chimney power plant [3].

Zhou Xinping [4] presented experiment and simulation results of a solar chimney thermal power generating equipment in China, and based on the simulation and the specific construction costs at a specific site, the optimum combination of chimney and collector dimensions was selected for the required electric power output. Ming et al. [5] presented a thermodynamic analysis of the solar chimney power plant and advanced energy utilization degree to analyze the performance of the system, which can produce electricity day and night. Ming et al. [6] developed a comprehensive model to evaluate the performance of a solar chimney power plant system in which the effects of various parameters on the relative static pressure, driving force,

power output and efficiency have been further investigated. The authors supposed the existing models are insufficient to accurately describe all the phenomena occurring in solar chimney power plant. Using the solar chimney prototype of Manzanares, as a practical example, 3D turbulent flow numerical simulation studies were performed to explore the geometrical modifications on the system performance. Results showed a good agreement with the analytical model. The control of the SCPP analytical tools such as dynamic simulation of these systems is essential. Ming et al. [7] to analyze the characteristics of heat transfer and airflow in the solar chimney power plant system with energy storage layer. Different mathematical models for the collector, the chimney and the energy storage layer were established, and the effect of solar radiation on the heat storage characteristic of the energy storage layer was analyzed. Numerical simulation results show that the heat storage decreases firstly and then increases with the increase of the solar radiation from 200W/m² to 800W/m². The static pressure decreases while the velocity increases significantly inside the system with the increase of solar radiation; the average temperature at the outlet of the chimney and the one of the energy storage layer may increase too significantly with the increase in solar radiation. In addition, the temperature gradient of the storage medium may increase and this results in an increase of energy loss from the bottom of the energy storage layer. Pastohr et al. [8] used the FLUENT software for modeling a solar chimney power plant, geometrically similar to that of Manzanares, with the aim of carrying out an analysis and reporting details on the operating mode and the system efficiency. They confirmed that the pressure drop in the turbine and the mass flow rate, decisive elements on the system effectiveness, cannot be only given by coupling all the parts of a SCPP. Numerical results given by FLUENT software are in good agreement with the results given by a

simple model proposed by the authors, which led to the conclusion that it is much easier to use it for parametric studies. Chergui et al. [9,10] simulated a thermohydrodynamicbehaviour analysis of the airflow through an axisymmetric system, such as chimneys, with defined boundary conditions.

II. MODELING

a. Geometric Mode

The three-dimensional geometric model of the SCPPS was built in GAMBIT, which is a pre-processor of FLUENT. The grid was also generated in GAMBIT [11]. The collector is 240m in diameter, and the distance between its covering and ground surface is 1.7m, the chimney is 200m in height and 10m in diameter.

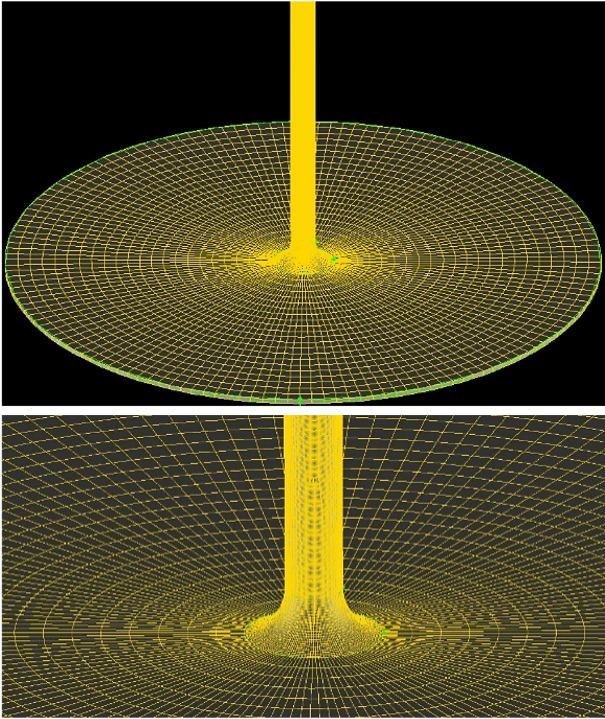


Fig.1 Grid model of the whole system

III. MATHEMATICAL MODEL

Based on the geometrical dimensions of the prototype Manzanares, a physical model for a solar chimney power plant was built. The basic equations including the models were numerically solved with the help of the commercial simulation program FLUENT [12]. The control equations including the continuity equation, momentum equation, energy equation, and turbulence equation (the standard k-ε equations) in the collector and chimney regions can be written as follows:

Continuity equation

$$\frac{\partial \rho}{\partial t} + \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0 \quad (1)$$

Navier-Stokes equation

$$\begin{aligned} \frac{\partial(\rho u)}{\partial t} + \frac{\partial(\rho uu)}{\partial x} + \frac{\partial(\rho uv)}{\partial y} + \frac{\partial(\rho uw)}{\partial z} \\ = -\frac{\partial p}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{\partial(\rho v)}{\partial t} + \frac{\partial(\rho vu)}{\partial x} + \frac{\partial(\rho vv)}{\partial y} + \frac{\partial(\rho vw)}{\partial z} \\ = -\frac{\partial p}{\partial y} + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) \end{aligned} \quad (3)$$

$$\begin{aligned} \frac{\partial(\rho w)}{\partial t} + \frac{\partial(\rho wu)}{\partial x} + \frac{\partial(\rho wv)}{\partial y} + \frac{\partial(\rho ww)}{\partial z} \\ = -\frac{\partial p}{\partial z} + \mu \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) \\ + \rho g \beta (T - T_0) \end{aligned} \quad (4)$$

Energy equation

$$\begin{aligned} \frac{\partial(\rho c T)}{\partial t} + \frac{\partial(\rho cu T)}{\partial x} + \frac{\partial(\rho cv T)}{\partial y} + \frac{\partial(\rho cw T)}{\partial z} \\ = \lambda \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right) \end{aligned} \quad (5)$$

k-ε equations

$$\begin{aligned} \frac{\partial(\rho k)}{\partial t} + \frac{\partial(\rho ku)}{\partial x} + \frac{\partial(\rho kv)}{\partial y} + \frac{\partial(\rho kw)}{\partial z} \\ = \frac{\partial}{\partial x} \left(\left(\mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial x} \right) \\ + \frac{\partial}{\partial y} \left(\left(\mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial y} \right) \\ + \frac{\partial}{\partial z} \left(\left(\mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial z} \right) + G_k + G_b - \rho \epsilon \\ + S_k \end{aligned} \quad (6)$$

$$\begin{aligned} \frac{\partial(\rho \epsilon)}{\partial t} + \frac{\partial(\rho \epsilon u)}{\partial x} + \frac{\partial(\rho \epsilon v)}{\partial y} + \frac{\partial(\rho \epsilon w)}{\partial z} \\ = \frac{\partial}{\partial x} \left(\left(\mu + \frac{\mu_t}{\sigma_\epsilon} \right) \frac{\partial \epsilon}{\partial x} \right) \\ + \frac{\partial}{\partial y} \left(\left(\mu + \frac{\mu_t}{\sigma_\epsilon} \right) \frac{\partial \epsilon}{\partial y} \right) + \frac{\partial}{\partial z} \left(\left(\mu + \frac{\mu_t}{\sigma_\epsilon} \right) \frac{\partial \epsilon}{\partial z} \right) \\ + C_{1\epsilon} G_k + C_{1\epsilon} C_{3\epsilon} G_b - C_{2\epsilon} \frac{\rho \epsilon^2}{k} + S_\epsilon \end{aligned} \quad (7)$$

G_k : represents the generation of turbulence kinetic energy due to the mean velocity gradients;

G_b : is the generation of turbulence kinetic energy due to buoyancy.

The constants have the following values [13]:

$$C_{1\epsilon} = 1.44, C_{2\epsilon} = 1.92, C_\mu = 0.09, \sigma_k = 1, \sigma_\epsilon = 1.3.$$

a. Boundary Conditions:

Settings of boundary conditions are shown in TABLE I. Pressure boundary condition was used to simulate the natural convection flow in the actual system. DO radiant model and convection heat transfer boundaries were used in this study (considering that air, has the heat transfer medium in the system, as thin optical thickness). The ground under collector covering roof that absorbs solar energy can be seen as a local heat source ($q_0 = G \cdot \tau \cdot \alpha$ W/m²). Ambient temperature T_0 is set at 293 K, the ground absorptivity is $\alpha = 0.9$ and the glass roof transmissivity is $\tau = 0.9$. Solar radiation intensity G has been changed.

TABLE I: The main boundary conditions

Place	Type	Value
The ground	Wall	$q_0 = G \cdot \tau \cdot \alpha$ (inner heat source)
Surface of the chimney	Wall	$q = 0$ W/m ²
Glass roof	Wall	$h=8$ W/(m ² K), $T_0 = 293$ K
Collector inlet	Pressure inlet	$T_0 = 293$ K, $\Delta P = 0$ Pa
Chimney outlet	Pressure outlet	$\Delta P = 0$ Pa

IV. RESULTS AND DISCUSSION

All numerical calculations had to be performed with the solver with double precision. The iteration error was at least 10^{-4} for all calculations, and was at least 10^{-6} for the energy equation. The solution converged in less than 600 iterations.

Figures 2–4 illustrate the temperature, velocity and pressure distributions in the solar collector of the solar chimney power plant at three different solar radiations.

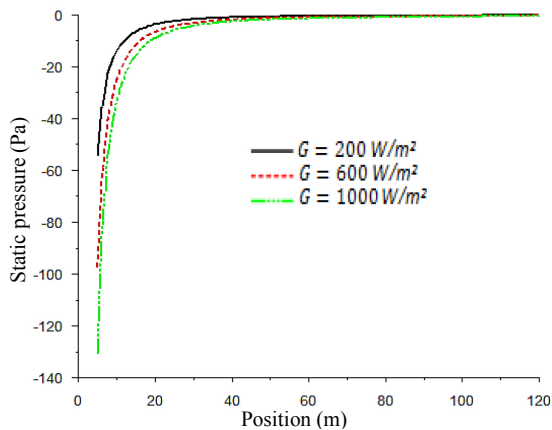


Fig.2 Static pressure profile of the fluid flowing through the collector.

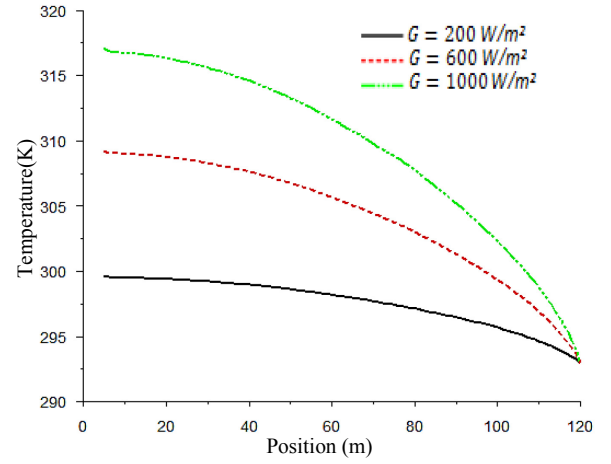


Fig.3 Temperature profile of the fluid flowing through the collector.

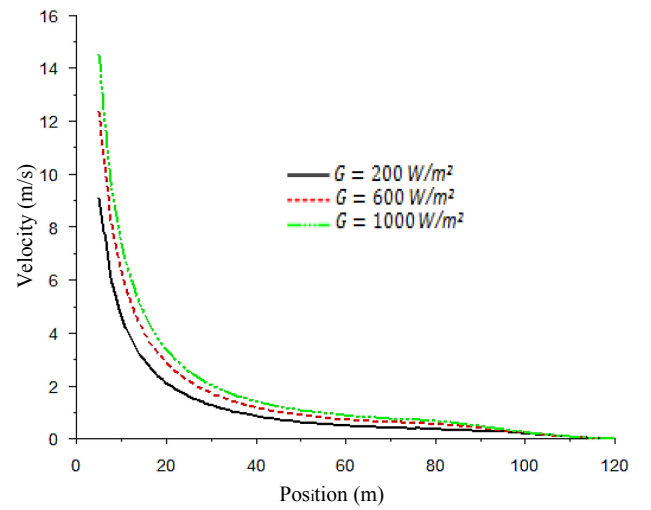


Fig.4 Velocity profile of the fluid flowing through the collector.

Figure 2 shows the static pressure profile, which decreases through the collector and drops dramatically near the chimney base. It also demonstrates that when the collector radius is constant the increasing in solar radiation results in a decrease in the static pressure.

Figure 3 illustrates that, when the solar radiation intensity increases, the air temperature increases for the same collector radius and when the solar radiation is constant, the temperature of fluid increases by decreasing the radius.

The velocity increases through the collector by decreasing the radius, but it increases more sharply by reaching the chimney base. When the collector radius is constant, an increase of solar radiation causes an increase of the air velocity, but the effect is not very significant (see Fig.4).

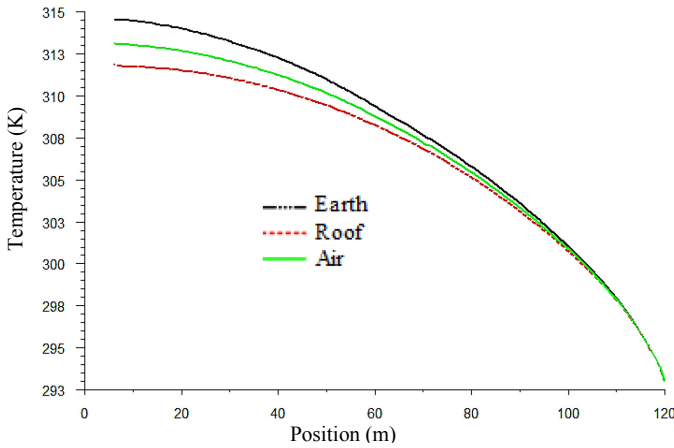


Fig.5 Temperature profiles of the earth, roof and air through the collector for $G=800 \text{ W/m}^2$.

Figure 5 illustrates the earth, roof and air temperature profiles through the collector. As shown in Figure 5, by decreasing the collector radius, all the temperatures increase, but the earth temperature increases more steeply.

TABLE II. Results of calculations for different solar radiations.

Solar radiation G (W/m^2)	Temperature difference between the inlet and outlet of collector (K)	Air velocity at outlet of collector (m/s)	Pressure difference between the inlet and outlet of collector (Pa)
200	6.62	9.10	54.343
400	11.77	10.97	77.86
600	16.25	12.37	97.58
800	20.31	13.52	115.04
1000	24.07	14.61	130.89

Simulative results (See Table II) show the relations between solar radiation intensity and three main parameters, including the differential pressure of collector, the air velocity of chimney base and the temperature difference between the inlet and outlet of collector. These three main parameters increase with the increasing solar radiation intensity. It's the reason that the SCPPS is always built in the countries or areas of which much more in annual mean sunshine.

To validate the numerical results, the temperature increase in the collector was compared with the experimental data of the Spanish prototype for 1000 w/m^2 [2]. As is shown in TABLE III, an acceptable quantitative agreement was obtained between the experimental data of the Manzanares prototype and both of the numerical results.

TABLE III. Comparison between the numerical results and the experimental data.

Results	Temperature increase	Air velocity at outlet of collector
Experimental data from Manzanares	20K	15 m/s
Our work	24.07K	14.61 m/s

V. CONCLUSION

A numerical simulation was performed with the help of FLUENT to analyze the characteristics of the flow for the geometry of the prototype in Manzanares, Spain, and both results are consistent with the experimental data of the Manzanares prototype. Numerical profiles for the temperature, velocity and pressure in the collector of the solar chimney power plant were shown for different solar radiations. It can be concluded that the pressure throughout system is negative value. The temperature difference between the inlet and outlet of collector is increase with the increase of solar radiation intensity, and increases by decreasing the radius. The velocity increases through the collector by decreasing the radius, and also an increase of solar radiation causes an increase of the air velocity. The calculated results are approximately equivalent to the relative experimental data of the Spanish prototype.

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NUMERICAL STUDY OF THE MIXED CONVECTION HEAT TRANSFER IN ANNULUS HEATED BY JOULEAN EFFECT

Submitted on 12/05/2014 – Accepted on 24/06/2014

Abstract

In the present work, we numerically study the three-dimensional mixed convection heat transfer in the annular space between two concentric horizontal pipes, the external pipe is heated by an electrical intensity passing through its small thickness while the inner cylinder is insulated. The convection in the fluid domain is conjugated to thermal conduction in the pipes solid thickness. The physical properties of the fluid are thermal dependant. The heat losses from the external outside pipe surface to the surrounding ambient are considered. The model equations of continuity, momenta and energy are numerically solved by a finite volume method with a second order spatiotemporal discretization. The obtained results show the three dimensional aspect of the thermal and dynamical fields with considerable variations of the viscosity and moderate variations of the fluid thermal conductivity. As expected, the mixed convection Nusselt number becomes more superior to that of the forced convection when the Grashof number is increased. At the solid-fluid interface, the results show clearly the azimuthal and axial variations of the local heat flux and the local Nusselt numbers. Following these results, we have tried modelling the average Nusselt number Nu_A as a function of Richardson number Ri . With the parameters used, the heat transfer is quantified by the correlation: $Nu_A = 9.9130 Ri^{0.0816}$.

Keywords: Mixed Convection, Annulus, Conjugate Heat Transfer, Numerical simulation.

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I. NOMENCLATURE

D_{1i}	Internal diameter of inner pipe, [m].	r^*	Nondimensional radial coordinate.
D_{1o}	External diameter of inner pipe, [m].	Re	Reynolds number, $(V_0 D_h / \nu_0)$.
D_{2i}	Internal diameter of outer pipe, [m].	Ri	Richardson number, (Gr/Re^2) .
D_{2o}	External diameter of outer pipe, [m].	t^*	Nondimensional time, $(V_0 t / D_h)$.
D_h	Hydraulic diameter, [m].	T^*	Nondimensional Temperature, $(T - T_0) / (G D_h^2 / K_s)$.
I	Electrical intensities, [A].	V_0	Axial mean velocity at the entrance, [m/s].
L	Pipe length, [m].	V_θ^*	Nondimensional circumferential velocity component, (V_θ / V_0) .
g	Gravitational acceleration, (= 9.81), $[m \cdot s^{-2}]$	V_r^*	Nondimensional radial velocity component, (V_r / V_0) .
G	Volumetric heat generation, $[Wm^{-3}]$	V_z^*	Nondimensional axial Velocity component, (V_z / V_0) .
G^*	Non-dimensional volumetric heat generation, $(K_s^* / Re_0 Pr_0)$.	z^*	Nondimensional axial coordinate, (z / D_h) .
Gr^*	Modified Grashof number, $(= g \beta G D_h^5 / K_s \nu^2)$		
h_r	Radiative heat transfer coefficient, $[W/m^2 \cdot ^\circ K]$.		
h_c	Convective heat transfer coefficient, $[W/m^2 \cdot ^\circ K]$.		
K^*	Nondimensional thermal conductivity, (K/K_0) .		
K_0	Fluid thermal conductivity at the entrance, $[W/m \cdot ^\circ K]$.		
K_s	Pipe thermal conductivity, $[W/m \cdot ^\circ K]$.		
$Nu(\theta, Z^*)$	Local Nusselt number.		
$Nu(Z^*)$	Axial Nusselt number.		
Nu_A	Average Nusselt number.		
P	Pressure, $[N/m^2]$.		
P^*	Nondimensional pressure, $(P - P_0) / \rho_0 V_0^2$.		
Pr	Prandtl number, (ν/α) .		
		Greek symbols	
		α	Thermal diffusivity, $[m^2 \cdot s^{-1}]$
		β	Thermal expansion coefficient, $[K^{-1}]$
		ε	Emissivity coefficient
		μ	Dynamic viscosity, $[kg \cdot m \cdot s^{-1}]$
		μ^*	Non-dimensional dynamic viscosity $(= \mu / \mu_0)$
		ν	Kinematic viscosity, $[m^2 \cdot s^{-1}]$
		θ	Angular coordinate, [rad]
		ρ	Density, $[kg \cdot m^{-3}]$
		σ	Stephan-Boltzmann constant $(= 5.67 \cdot 10^{-8})$,

	[W·m ⁻² ·K ⁻⁴]
τ	Stress, [N·m ⁻²]
τ^*	Non-dimensional stress ($= \tau / (\mu_0 V_0 / D_i)$)

II. INTRODUCTION

Laminar mixed convection between two concentric pipes has been studied by several workers. Nguyen et al. [1], studied theoretically the water flow in a concentric annulus, the surfaces of the system are considered isothermal and the pressure gradient along the annulus is constant. The governing system of equations is solved by the finite difference method. The results are obtained from a water temperature between 0 and 150°C, this temperature range corresponds to a Prandtl number between 1 and 14. The author has shown that the axial flow is influenced by the natural convection, thereby changing the axisymmetric shape of the velocity field and temperature. The effect of the Prandtl number of the axial flow is presented for the case of Ra=104 and radius ratio Re/Ri =2. The obtained results show that the increasing of the Prandtl number make the axial velocity fields close to that of the forced convection. A good agreement is obtained with existing experimental and numerical results. Kotake et al [2], studied numerically the same problem, two different boundary conditions: a constant heat flux, constant temperature of the outer wall. The numerical results of average Nusselt number is in good agreement with other experimental results. Similar works have been done numerically by Kumar [3], and Chung et al. [4], Nouar [5], where the ratio D₀/D₁ was considered. In the work of Habib et al [6], the inner cylinder subjected to a non-uniform heat flux, while the outer surface is adiabatic, the change in axial Nusselt number in this work is in good agreement that of a numerical study under the same condition.

Experimentally, the heat transfer by mixed convection in an annulus was studied by Mohammed et al [7], the two concentric cylinders are made of steel, D₀/D₁ = 2, the inner tube subjected to constant heat flux, the outer tube is adiabatic, the Reynolds number is varied from 200 to 1000, while the Grashof number variation is between 6.2 · 10⁵ and 1.2 · 10⁷, the results show that the average Nusselt number can be linked with different dimensionless numbers by the correlation: $Nu_m = 2.964(Gr \cdot Pr/Re)^{0.0326}$

In this work, we studied numerically the heat transfer by mixed convection in an annulus between two concentric cylinders, the physical properties of the fluid are thermodynamic and the heat losses with the external environment are considered. The objective of our study is the correlation of average Nusselt numbers and Richardson.

III. THE GEOMETRY AND MATHEMATICAL MODEL

Fig.1 illustrates the problem geometry. We consider a long two horizontal concentric pipes having a length L = 1 m. The internal pipe with an inside diameter D_{1i} = 0.96 cm and an external diameter D_{1o} = 1 cm, the external pipe with an inside diameter D_{2i} = 2 cm and an external diameter D_{2o} = 2.04 cm. The hydraulic diameter D_h = D_{2i} - D_{1o} = 1 cm. The

pipes are made of Inconel having a thermal conductivity K_s = 20W/m°K.

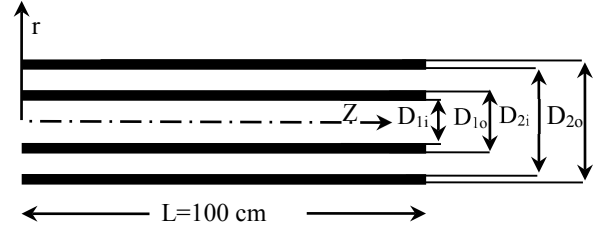


Fig. 1 Geometry of the Problem

The passing of an electrical intensity along the thickness of external pipe produced a generation of heat by the Joule effect, the considered electrical intensity values are: I =40, 45, 50, 55, 60 and 65 Amperes. This heat is transferred to laminar incompressible flow of distilled water with an average velocity equal to 5.69 10⁻² m/s in the annulus. The inside surface of internal pipe is insulated, at the outer surface of external pipe, the heat losses by radiation and natural convection to the surrounding air are taken into account. At the annulus entrance, we have a uniform temperature equal to 288K, the Reynolds number Re is equal to 500, the Prandtl number Pr is equal to 8.082 and the Grashof numbers Gr correspond to the electrical intensities are: 55734, 70538, 87084, 105372, 125401, and 147173, respectively. The non-dimensional fluid viscosity and thermal conductivity variation with temperature are represented by the functions $\mu^*(T^*)$ and $K^*(T^*)$ obtained by smooth fittings of the tabulated values cited by Baehr and Stephan [8]. The combined heat transfer in the solid and fluid domains is a conjugate heat transfer problem. The physical principles involved in this problem are well modelled by the following non dimensional conservation partial differential equations with their initial and boundary conditions:

A. Modelling Equations

$$\text{At } t^* = 0, \quad V_r^* = V_\theta^* = V_z^* = T^* = 0 \quad (1)$$

At $t^* > 0$,

1) Mass Conservation Equation

$$\frac{1}{r^*} \frac{\partial}{\partial r^*} (r^* V_r^*) + \frac{1}{r^*} \frac{\partial V_\theta^*}{\partial \theta} + \frac{\partial V_z^*}{\partial z^*} = 0 \quad (2)$$

2) Radial Momentum Conservation Equation

$$\begin{aligned} \frac{\partial V_r^*}{\partial t^*} + \frac{1}{r^*} \frac{\partial}{\partial r^*} (r^* V_r^* V_r^*) + \frac{1}{r^*} \frac{\partial}{\partial \theta} (V_\theta^* V_r^*) + \\ \frac{\partial}{\partial z^*} (V_z^* V_r^*) - \frac{V_\theta^{*2}}{r^*} = - \frac{\partial P^*}{\partial r^*} + \frac{Gr_0^*}{Re_0^2} \cos \theta T^* + \\ \frac{1}{Re_0} \left[\frac{1}{r^*} \frac{\partial}{\partial r^*} (r^* \tau_{rr}^*) + \frac{1}{r^*} \frac{\partial}{\partial \theta} (\tau_{r\theta}^*) - \frac{\tau_{\theta\theta}^*}{r^*} + \frac{\partial}{\partial z^*} (\tau_{rz}^*) \right] \end{aligned} \quad (3)$$

3) Angular Momentum Conservation Equation

$$\begin{aligned} & \frac{\partial V_\theta^*}{\partial t^*} + \frac{1}{r^*} \frac{\partial}{\partial r^*} (r^* V_r^* V_\theta^*) + \frac{1}{r^*} \frac{\partial}{\partial \theta} (V_\theta^* V_\theta^*) + \\ & \frac{\partial}{\partial z^*} (V_z^* V_\theta^*) + \frac{V_r^* V_\theta^*}{r^*} = -\frac{1}{r^*} \frac{\partial P^*}{\partial \theta} \quad (4) \\ & \frac{Gr_0^*}{Re_0^2} \sin \theta \quad T^* + \frac{1}{Re_0} \left[\frac{1}{r^{*2}} \frac{\partial}{\partial r^*} (r^{*2} \tau_{\theta r}^*) + \right. \\ & \left. \frac{1}{r^*} \frac{\partial}{\partial \theta} (\tau_{\theta \theta}^*) + \frac{\partial}{\partial z^*} (\tau_{\theta z}^*) \right] \end{aligned}$$

4) Axial Momentum Conservation Equation

$$\begin{aligned} & \frac{\partial V_z^*}{\partial t^*} + \frac{1}{r^*} \frac{\partial}{\partial r^*} (r^* V_r^* V_z^*) + \frac{1}{r^*} \frac{\partial}{\partial \theta} (V_\theta^* V_z^*) + \\ & \frac{\partial}{\partial z^*} (V_z^* V_z^*) = -\frac{\partial P^*}{\partial z^*} + \\ & \frac{1}{Re_0} \left[\frac{1}{r^*} \frac{\partial}{\partial r^*} (r^* \tau_{rz}^*) + \frac{1}{r^*} \frac{\partial}{\partial \theta} (\tau_{\theta z}^*) + \frac{\partial}{\partial z^*} (\tau_{zz}^*) \right] \quad (5) \end{aligned}$$

5) Energy Conservation Equation

$$\begin{aligned} & \frac{\partial T^*}{\partial t^*} + \frac{1}{r^*} \frac{\partial}{\partial r^*} (r^* V_r^* T^*) + \frac{1}{r^*} \frac{\partial}{\partial \theta} (V_\theta^* T^*) + \\ & \frac{\partial}{\partial z^*} (V_z^* T^*) = G^* - \\ & \frac{1}{Re_0 Pr_0} \left[\frac{1}{r^*} \frac{\partial}{\partial r^*} (r^* q_r^*) + \right. \\ & \left. \frac{1}{r^*} \frac{\partial}{\partial \theta} (q_\theta^*) + \frac{\partial}{\partial z^*} (q_z^*) \right] \quad (6) \end{aligned}$$

Where $G^* = \begin{cases} K_s^* / (Re_0 Pr_0) & \text{in the solid} \\ 0 & \text{in the fluid} \end{cases}$

The viscous stress tensor components are:

$$\begin{aligned} \tau_{rr}^* &= 2\mu^* \frac{\partial V_r^*}{\partial r^*}, \quad \tau_{r\theta}^* = \tau_{\theta r}^* = \mu^* \left[r^* \frac{\partial}{\partial r^*} \left(\frac{V_\theta^*}{r^*} \right) + \frac{1}{r^*} \frac{\partial V_r^*}{\partial \theta} \right] \\ \tau_{\theta\theta}^* &= 2\mu^* \left[\frac{1}{r^*} \frac{\partial V_\theta^*}{\partial \theta} + \frac{V_r^*}{r^*} \right], \quad \tau_{\theta z}^* = \tau_{z\theta}^* = \mu^* \left[\frac{\partial V_\theta^*}{\partial z^*} + \frac{1}{r^*} \frac{\partial V_z^*}{\partial \theta} \right] \quad (7) \\ \tau_{zz}^* &= 2\mu^* \frac{\partial V_z^*}{\partial z^*}, \quad \tau_{zr}^* = \tau_{rz}^* = \mu^* \left[\frac{\partial V_z^*}{\partial r^*} + \frac{1}{r^*} \frac{\partial V_r^*}{\partial z^*} \right] \end{aligned}$$

The heat fluxes are:

$$q_r^* = -K^* \frac{\partial T^*}{\partial r^*}, \quad q_\theta^* = -\frac{K^*}{r^*} \frac{\partial T^*}{\partial \theta} \quad \text{and} \quad q_z^* = -K^* \frac{\partial T^*}{\partial z^*} \quad (8)$$

B. The Boundary Conditions

1) At the Annulus Entrance : $Z^*=0$

In the Fluid Domain: $0.5435 \leq r^ \leq 1.0435$ and $0 \leq \theta \leq 2\pi$

$$V_r^* = V_\theta^* = T^* = 0, V_z^* = 1 \quad (9)$$

*In the Solid Domain:

$$0.5 \leq r^* \leq 0.5435 \quad \text{or} \quad 1.0435 \leq r^* \leq 1.0870 \quad \text{and} \quad 0 \leq \theta \leq 2\pi$$

$$V_r^* = V_\theta^* = V_z^* = T^* = 0 \quad (10)$$

2) At the Annulus Exit : $Z^*=217.39$

In the Fluid Domain: $0.5435 \leq r^ \leq 1.0435$ and $0 \leq \theta \leq 2\pi$

$$\frac{\partial V_r^*}{\partial z^*} = \frac{\partial V_\theta^*}{\partial z^*} = \frac{\partial V_z^*}{\partial z^*} = \frac{\partial}{\partial z^*} \left(K^* \frac{\partial T^*}{\partial z^*} \right) = 0 \quad (11)$$

*In the Solid Domain:

$$0.5 \leq r^* \leq 0.5435 \quad \text{or} \quad 1.0435 \leq r^* \leq 1.0870 \quad \text{and} \quad 0 \leq \theta \leq 2\pi$$

$$V_r^* = V_\theta^* = V_z^* = \frac{\partial}{\partial z^*} \left(K^* \frac{\partial T^*}{\partial z^*} \right) = 0 \quad (12)$$

3) At the Inside Wall of Internal Pipe: $r^*=0.5$

$$V_r^* = V_\theta^* = V_z^* = 0 \quad \text{and} \quad \frac{\partial T^*}{\partial r^*} = 0 \quad (13)$$

4) At the Outer Wall of External Pipe: $r^*=1.0870$

$$\begin{cases} V_r^* = V_\theta^* = V_z^* = 0 \\ -K^* \frac{\partial T^*}{\partial r^*} = \frac{(h_r + h_c) D_i}{K_0} T^* \end{cases} \quad (14)$$

$$h_r = \varepsilon \sigma (T^2 + T_\infty^2) (T + T_\infty) \quad (15)$$

The emissivity of the outer wall ε is arbitrarily chosen to 0.9 while h_c is derived from the correlation of Churchill and Chu [9] valid for all Pr and for Rayleigh numbers in the range $10^{-6} \leq Ra \leq 10^9$.

$$\begin{aligned} Nu &= [h_c D_i / K_{air}] \\ &= \left[0.6 + \left(0.387 Ra^{1/6} / (1 + (0.559 / Pr_{air})^{9/16})^{8/27} \right)^2 \right] \quad (16) \end{aligned}$$

C. Nusselt Number

At the solid-fluid interface ($r^*=1.0435$) the local Nusselt number is defined as:

$$Nu(\theta, Z^*) = \frac{h(\theta, Z^*) D}{k} = \frac{1}{[T^*(r^*, \theta, z^*) - T_m^*(z^*)]} \quad (17)$$

The axial Nusselt number is defined as:

$$Nu(z^*) = \frac{1}{2\pi} \int_0^{2\pi} Nu(\theta, z^*) d\theta \quad (18)$$

The average Nusselt number for the whole solid-fluid interface is defined as:

$$Nu_A = \frac{1}{(2\pi)(217.39)} \int_0^{2\pi} \int_0^{217.39} Nu(\theta, z^*) dz^* d\theta \quad (19)$$

IV. THE NUMERICAL METHOD

For the numerical solution of modelling equations, we used the finite volume method well described by Patankar [10]. The using of this method involves the discretization of the physical domain into a discrete domain constituted of finite volumes where the modelling equations are discretized in a typical volume. We used a temporal discretization with a truncation error of $(\Delta t^*)^2$ order. The mesh used contains $26 \times 44 \times 162$ points in the radial, azimuthal and axial directions. The considered time step is $\Delta t^* = 5 \cdot 10^{-4}$. The

accuracy of the results of our numerical code has been tested by the comparison of our results with those of Nouar[11] who studied numerically the effect of the dynamic viscosity of the mixed convection between two concentric horizontal pipes. The inner cylinder and the outer cylinder are subjected to a constant heat flux. The controlling parameters of the problem are: $Re = 35$, $Pr = 557.3$, $Gr = 6000$, $L/D_h = 125$. In Fig. 2 we illustrate the axial temperature variation at the top ($\theta = 0$) and bottom ($\theta = \pi$) of the external interface (fluid-outer pipe).

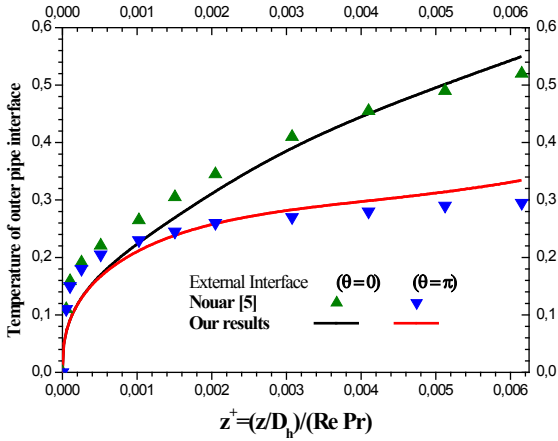


Fig. 2 Axial Evolution of the interface temperature (fluid-Outer pipe); a Comparison with the Results of Nouar[5].

It is seen that there is a good agreement between our results and theirs.

V. RESULTS AND DISCUSSIONS

A. Development of the Secondary Flow

The obtained flow for the considered cases is characterized by a main flow in the axial direction and a secondary flow in the (\vec{r}, θ) plane. Qualitatively we note the similarity of results for the six study cases. Quantitatively, the effect of mixed convection becomes increasingly important with the increase of volumetric heating. For this, the figures presented are those of the higher volumetric heating, case of $Gr = 147173$. In fig. 3, we present the secondary flow at the annulus exit ($Z^* = 100$). The transverse movement is explained as follows: the hot fluid moves along the hot wall from the bottom of the outer tube ($\theta = \pi$) upwards ($\theta = 0$) and moves down from the top to the bottom along the inner tube. The vertical plane passing through the angles ($\theta = 0$) and ($\theta = \pi$) is a plane of symmetry.

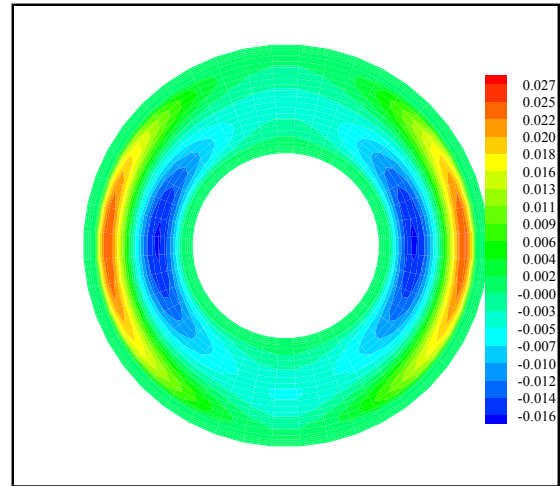


Fig. 3 Secondary Flow at the Exit of the Annulus for

$Gr = 147173$

The transverse flow in the (\vec{r}, θ) plane is represented by two similar but counter rotating cells. We noticed that the centre of the rotating cells moves downward continuously along the axial direction.

B. Development of the Axial Flow

At the entrance, the axial flow is axisymmetric, after this latter is influenced by the transverse movement of the fluid. The maximum axial velocity is all the time at the top of the annulus because the fluid viscosity decreased from bottom to top. In fig. 4, we present the axial flow distribution at the exit of the annulus.

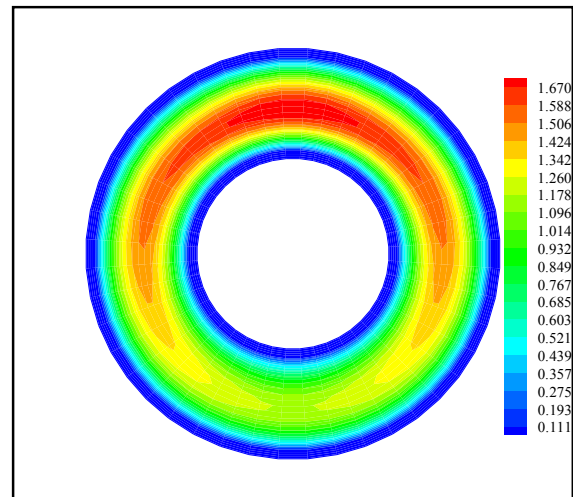


Fig. 4 Axial Velocity Profiles at the Exit of the Annulus

for $Gr = 147173$

C. Development of the Temperature Field

In the reference case (forced convection), the distribution of the fluid temperature in the absence of transverse motion is axisymmetric. For a given section, the isotherms are concentric circles with a maximum temperature on the inner wall of the external cylinder and a minimum temperature on the outer wall of the internal cylinder. In the presence of volumetric heating, a transverse flow exists and thus changes

the axisymmetric distribution of fluid and pipe wall temperature and gives it an angular variation, this variation explained as follows: the hot fluid near the hot pipe wall moves upwards under the buoyancy force effect, the relatively cold fluid descends down near the internal pipe. This movement of the secondary flow is the cause of the azimuthally temperature variation. The obtained results show that at given section, the maximum temperature T^* is all the time located at $r^*=1$ and $\theta=0$ (top of solid-fluid interface), because the hot fluid is driven by the secondary motion towards the top of the annulus. The minimum temperature is within the core fluid, in the lower part of the annulus at $\theta=\pi$. In fig. 5, we present the polar temperature distribution at the exit of the annulus for $Gr=147173$.

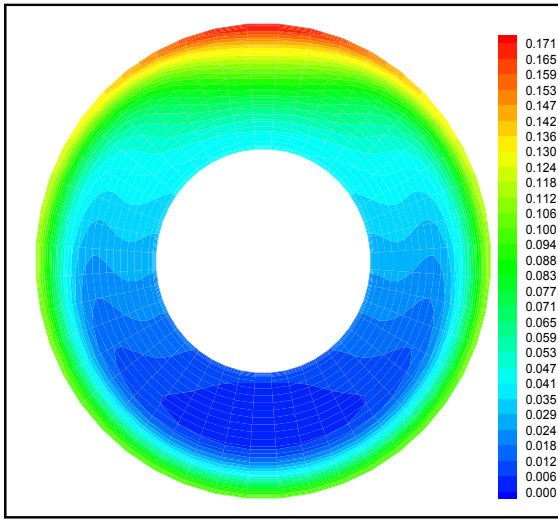


Fig. 5 The Isotherms at the Exit of the Annulus for $Gr=147173$

D. The Nusselt numbers

The phenomenon of heat transfer has been characterised in terms of circumferentially Nusselt numbers calculated at the inner wall of external pipe, which is obtained by (19). The variation of local Nusselt number of the solid-fluid interface is presented in fig. 8 for $Gr=147173$. From the entrance to the exit, we notice the large axial and angular variations of local Nusselt numbers, it takes a minimum value at ($\theta=0$) and maximum value at ($\theta=\pi$).

Fig. 9 shows the axial variation of Nusselt number for the seven studied cases. At the zone of entrance, the axial Nusselt number decreases rapidly for all studied cases. After, it increases and takes maximum value at the exit of annulus equal to: 7.58, 7.96, 8.35, 8.74, 9.06 and 9.45 for $Gr = 55734, 70538, 87084, 105372, 125401, \text{ and } 147173$ respectively. The axial Nusselt numbers increases with the increase of volumetric heating.

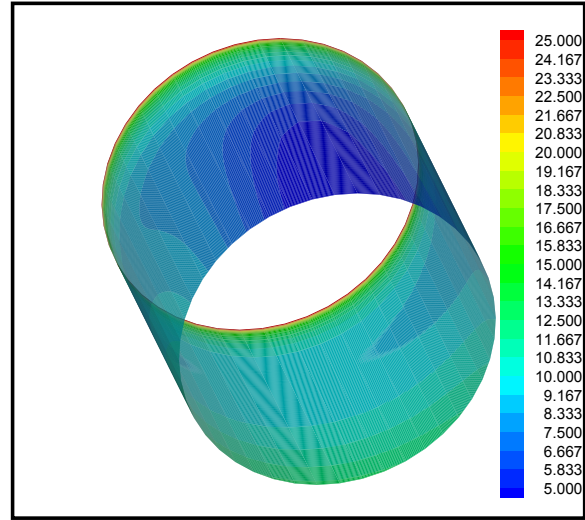


Fig. 8 The Local Nusselt Number Variation for $Gr = 147173$.

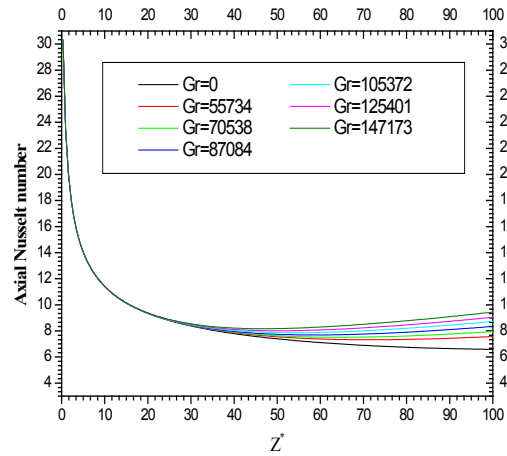


Fig. 9 Nusselt Number Variation for Different Grashof Numbers

In Tab. 1 we present the average Nusselt numbers of all studied cases:

TABLE I. Average Nusselt Numbers

Gr	55734	70538	87084	105372	125401	147173
Ri	0.223	0.282	0.348	0.421	0.502	0.589
Nu_A	8.803	8.928	9.068	9.220	9.359	9.529

The results obtained allowed us to model the average Nusselt number of the mixed convection in function of Richardson number, we found that the results with the parameters used are correlated with the correlation:

$$Nu_A = 9.9130 Ri^{0.0816} (22)$$

VI. CONCLUSION

This study considers the numerical simulation of the three dimensional mixed convection heat transfer in horizontal annulus, the external pipe is heated by an electrical intensity passing through its small thickness and the internal pipe is insulated. The obtained results show that:

* The dynamic and thermal fields for mixed convection are qualitatively and quantitatively different from those of forced convection.

* Although the volumetric heat input in the solid thickness is constant, the heat flux at the solid-fluid interface is not constant: it varies with θ and z , that is a characteristic of the considered mixed convection.

* The azimuthally variation of temperature at a given section is important; this phenomenon is demonstrated by the circumferential temperature variation of the wall. There is a large temperature wall difference between top and bottom of the external pipe.

* The physical properties are thermo-dependent (the dimensionless dynamic viscosity varies from 1.018 at the entrance to 0.4171 at the exit).

* For the forced convection, the average Nusselt number is 8.803. Thus, for the mixed convection, the parameters used are well correlated with the correlation: $NU_A = 9.9130 Rf^{0.0816}$.

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MINERALOGICAL CHARACTERIZATION OF SANDSTONE AND CLAY, NORTH-EAST CONSTANTINE.

Submitted on 08/03/2014 – Accepted on 19/12/2015

Abstract

The north-east area of Constantine has a very complex geological setting. The variety of sedimentary rocks such as sandstone and clay in abundance, represent a big importance in the industry and road infrastructure.

The X-ray diffraction (XRD) analysis, Scanning Electron Microscopy SEM/EDS, FTIR spectroscopy of sandstone and clay are required for qualitative and quantitative analysis of the existing phases.

In addition, chemical analysis of the same samples is required to confirm the XRD, EDS (Energy Dispersive X ray Spectroscopy) and FTIR spectroscopy results.

The results of this multidisciplinary study, obtained by various analytical techniques, show a good agreement on the existing phases.

Keywords: Sandstone, Clay, XRD, SEM/EDS, FTIR

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NOMENCLATURE

a	Defined constant in the elliptic coordinates, (distance to the poles). (m)
c_p	Specific heat at constant pressure. (J.kg ⁻¹ .K ⁻¹)
e_1	Eccentricity of the internal ellipse.
Fr	Geometrical factor of form
\vec{g}	Gravitational acceleration. (m.s ⁻²)
Gr	Grashof number defined by $Gr = \frac{g\beta a^3}{\nu^2} \Delta T$
h	Dimensional metric coefficient. (m)
H	Dimensionless metric coefficient.
Nu	Local Nusselt number.
\overline{Nu}	Average Nusselt number.
P	Stress tensor.
Pr	Prandtl number defined by $Pr = \frac{\nu \rho c_p}{\lambda}$
S_Φ	Source term.
T	Fluid's temperature. (K)
T_1	Hot wall temperature. (K)
T_2	Cold wall temperature. (K)
ΔT	Temperature deference. $\Delta T = T_1 - T_2$. (K)
$V_{\eta, \theta}$	Velocity components according to η and θ . (m.s ⁻¹)
\vec{V}	Velocity vector. (m.s ⁻¹)

Greek letters

α	Inclination angle. (°)
β	Thermal expansion coefficient. (K ⁻¹)
Γ_Φ	Diffusion coefficient.
λ	Thermal conductivity of the fluid. (W.m ⁻¹ .K ⁻¹)
ν	kinematic viscosity. (m ² .s ⁻¹)
ρ	Density. (kg.m ⁻³)

η, θ, z	Elliptic coordinates.
ψ	function of current. (m ² .s ⁻¹)
ω	vorticity. (s ⁻¹)
φ	General function.

Superscripts

+ dimensionless parameters.

Subscripts

i	Inner.
e	Outer.
éq	Equivalent
Ni	Points number along the coordinate η
NN	Points number along the coordinate θ
η	According to the coordinate η
θ	According to the coordinate θ

1. INTRODUCTION

The study of heat transfer by natural convection, in the annular spaces formed by elliptic cylinders with horizontal axes centered or eccentric, has given rise to many works include such as Zhu et al. (2004) who have made a numerical study into the annulus between two centered elliptic cylinders, using D.Q method (Differential Quadrature) to solve their equations. Djeddar el al. (2004), (2005) and (2006) mean while, have studied numerically natural convection in an annulus formed by two elliptical cylinders and horizontal axes confocal using the formulation in primitive variables, they could detect multi-cellular flows when Grashof number increases, for certain geometries, and for the three parietal thermal conditions used.

In this work we propose a numerical simulation using the finite-volume method described by Patankar (1980), the elliptic coordinates cited by Moon (1961) and the vorticity stream-function formulation illustrated by Nogotov (1978) to solve the equations governing the phenomenon studied. The mesh adopted for the execution of our calculations is (101x111).

2. Theoretical analysis

We consider an annular space, filled with a Newtonian fluid (in this case air), located between two elliptical cylinders, and two horizontal and centered diametrical planes. Figure 1 represents a cross-section of the system.

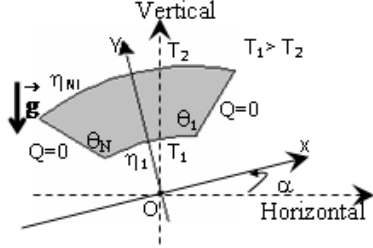


FIG. 1 Cross-section of the system

Both lower and upper walls are elliptical, isothermal and respectively maintained at temperatures T_1 and T_2 with $T_1 > T_2$. The two diametrical plans are adiabatic.

It occurs in the enclosure natural convection that we propose to study numerically.

We consider an incompressible fluid flow, two dimensional, permanent and laminar with constant physical properties and we use the approximation of Boussinesq which considers the variations of the density ρ negligible at all terms of the momentum equations except in the term of gravity whose variations with temperature supposed linear, generate the natural convection.

Viscous dissipation and the work of pressure forces are negligible in the heat equation; the radiation is not considered.

With these assumptions the equations governing our problem can be written in vectorial form as follows:

- Continuity equation:

$$\text{div } \vec{V} = 0 \quad (1)$$

- Momentum equation:

$$(\vec{V} \cdot \text{grad}) \vec{V} = \frac{\rho}{\rho_0} \vec{g} + \frac{\nabla P}{\rho_0} \quad (2)$$

- Heat equation:

$$(\vec{V} \cdot \text{grad}) T = \frac{\lambda}{\rho c_p} \nabla^2 T \quad (3)$$

It is convenient to define a reference frame such as the limits of the system result in constant values of the coordinates. The coordinates known as "elliptic" (η, θ) allow, precisely in our case to obtain this result. Thus the

two elliptic isothermal walls will be represented by η_1 and η_{N1} and the two adiabatic walls will be represented by θ_1 and θ_{N1} . The transition from Cartesian coordinates to elliptic coordinates is done using the following relations:

$$\begin{cases} x = a \cdot \text{ch}(\eta) \cdot \cos(\theta) \\ y = a \cdot \text{sh}(\eta) \cdot \sin(\theta) \end{cases}$$

The equations (1), (2) and (3) are written respectively:

$$\frac{\partial}{\partial \eta} (h V_\eta) + \frac{\partial}{\partial \theta} (h V_\theta) = 0 \quad (5)$$

$$\frac{V_\eta}{h} \frac{\partial \omega}{\partial \eta} + \frac{V_\theta}{h} \frac{\partial \omega}{\partial \theta} =$$

$$\begin{aligned} & \frac{g\beta}{h} \left\{ \begin{aligned} & [F(\eta, \theta) \cos(\alpha) - G(\eta, \theta) \sin(\alpha)] \frac{\partial T}{\partial \eta} \\ & - [F(\eta, \theta) \sin(\alpha) + G(\eta, \theta) \cos(\alpha)] \frac{\partial T}{\partial \theta} \end{aligned} \right\} \\ & + \frac{\nu}{h^2} \left(\frac{\partial^2 \omega}{\partial \eta^2} + \frac{\partial^2 \omega}{\partial \theta^2} \right) \end{aligned} \quad (6)$$

$$V_\eta \frac{\partial T}{\partial \eta} + V_\theta \frac{\partial T}{\partial \theta} = \frac{\lambda}{\rho c_p} \frac{1}{h} \left(\frac{\partial^2 T}{\partial \eta^2} + \frac{\partial^2 T}{\partial \theta^2} \right) \quad (7)$$

With the introduction of vorticity defined by:

$$\omega = -\frac{1}{h^2} \left(\frac{\partial^2 \psi}{\partial \eta^2} + \frac{\partial^2 \psi}{\partial \theta^2} \right) \quad (8)$$

After the introduction of the stream-function, in order to check the continuity equation identically.

$$\left. \begin{aligned} h &= a \left(\text{sh}^2(\eta) + \sin^2(\theta) \right)^{1/2} \\ F(\eta, \theta) &= \frac{\text{sh}(\eta) \cos(\theta)}{\left(\text{sh}^2(\eta) + \sin^2(\theta) \right)^{1/2}} \\ G(\eta, \theta) &= \frac{\text{ch}(\eta) \sin(\theta)}{\left(\text{sh}^2(\eta) + \sin^2(\theta) \right)^{1/2}} \end{aligned} \right\} \quad (9)$$

By posing the following adimensional quantities:

$D_h = a$ (arbitrarily selected focal distance)

$$\begin{aligned} H &= \frac{h}{D_h}, \quad V_\eta^+ = V_\eta \frac{D_h}{\nu}, \quad V_\theta^+ = V_\theta \frac{D_h}{\nu}, \quad \omega^+ = \omega \frac{D_h^2}{\nu}, \\ \psi^+ &= \frac{\psi}{\nu} \quad \text{and} \quad T^+ = \frac{T - T_2}{T_1 - T_2} \end{aligned}$$

The equations (5), (6), (7) and (8) becomes:

$$\frac{\partial}{\partial \eta} (H V_\eta^+) + \frac{\partial}{\partial \theta} (H V_\theta^+) = 0 \quad (10)$$

$$\frac{V_{\eta}^{+}}{H} \frac{\partial \omega^{+}}{\partial \eta} + \frac{V_{\theta}^{+}}{H} \frac{\partial \omega^{+}}{\partial \theta} = \frac{Gr}{H} \left\{ \begin{array}{l} [F(\eta, \theta) \cos(\alpha) - G(\eta, \theta) \sin(\alpha)] \frac{\partial T^{+}}{\partial \eta} \\ - [F(\eta, \theta) \sin(\alpha) + G(\eta, \theta) \cos(\alpha)] \frac{\partial T^{+}}{\partial \theta} \end{array} \right\} + \frac{1}{H^2} \left(\frac{\partial^2 \omega^{+}}{\partial \eta^2} + \frac{\partial^2 \omega^{+}}{\partial \theta^2} \right) \quad (11)$$

$$HV_{\eta}^{+} \frac{\partial T^{+}}{\partial \eta} + HV_{\theta}^{+} \frac{\partial T^{+}}{\partial \theta} = \frac{1}{P_r} \left(\frac{\partial^2 T^{+}}{\partial \eta^2} + \frac{\partial^2 T^{+}}{\partial \theta^2} \right) \quad (12)$$

$$\omega^{+} = - \frac{1}{H^2} \left[\frac{\partial^2 \psi^{+}}{\partial \eta^2} + \frac{\partial^2 \psi^{+}}{\partial \theta^2} \right] \quad (13)$$

The boundary conditions are: For the elliptical hot wall ($\eta = \eta_i = \text{constant}$) we have:

$$V_{\eta}^{+} = V_{\theta}^{+} = \frac{\partial \psi^{+}}{\partial \theta} = \frac{\partial \psi^{+}}{\partial \eta} = 0, \quad T_1^{+} = 1 \text{ and}$$

$$\omega^{+} = - \frac{1}{H^2} \left[\frac{\partial^2 \psi^{+}}{\partial \eta^2} + \frac{\partial^2 \psi^{+}}{\partial \theta^2} \right] \text{ and for the cold elliptic wall}$$

($\eta = \eta_{NN} = \text{constant}$) we have:

$$V_{\eta}^{+} = V_{\theta}^{+} = \frac{\partial \psi^{+}}{\partial \theta} = \frac{\partial \psi^{+}}{\partial \eta} = 0, \quad T_2^{+} = 0 \text{ and}$$

$$\omega^{+} = - \frac{1}{H^2} \left[\frac{\partial^2 \psi^{+}}{\partial \eta^2} + \frac{\partial^2 \psi^{+}}{\partial \theta^2} \right]. \text{ For the two diametrical plans}$$

($\theta = \theta_i = \text{constant}$ and $\theta = \theta_{NN} = \text{constant}$) we have:

$$V_{\eta}^{+} = V_{\theta}^{+} = \frac{\partial \psi^{+}}{\partial \theta} = \frac{\partial \psi^{+}}{\partial \eta} = 0, \quad \frac{\partial T^{+}}{\partial \theta} = 0 \text{ and}$$

$$\omega^{+} = - \frac{1}{H^2} \left[\frac{\partial^2 \psi^{+}}{\partial \eta^2} + \frac{\partial^2 \psi^{+}}{\partial \theta^2} \right]$$

Once the temperature distribution is obtained; local Nusselt number value is given by the following relation:

$$Nu = - \frac{1}{H} \frac{\partial T^{+}}{\partial \eta} \Big|_{\eta = cste} \quad (14)$$

The average Nusselt number is expressed by:

$$\overline{Nu} = \frac{1}{\theta_{NN} - \theta_i} \int_{\theta_i}^{\theta_{NN}} Nu d\theta \quad (15)$$

2. 1 Numerical Formulation

To solve the system of equations (11), (12) and boundary conditions, we consider a numerical solution by the finite volumes method. Where as for the equation (13), we

consider a numerical solution by the centered differences method.

Both methods are widely used in the numerical solution of transfer problems; they are well exposed by Patankar (1980) and by Nogotov (1978). Figure 2 represents the physical and computational domain.

We cut out annular space according to the directions η and θ from the whole of elementary volumes or "control volume" equal to " $H^2 \cdot \Delta \eta \cdot \Delta \theta \cdot 1$ ". (The problem is two-dimensional, the thickness in Z direction is assumed to the unity).

The center of a typical control volume is a point P and center of its side faces "east", "west", "north" and "south", are indicated respectively, by the letters e, w, n and s. Four other control volumes surround each interior control volume. The centers of these volumes are points E, W, N and S. the scalar variables (vorticity, temperature) are stored at centered points in control volumes. Thus transfer equations of scalar variables are integrated in typical control volume.

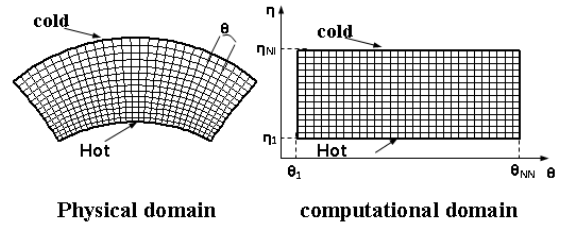


FIG. 2 Physical and computational domain

Figure 3 represents a typical control volume and its neighbors in a computational domain.

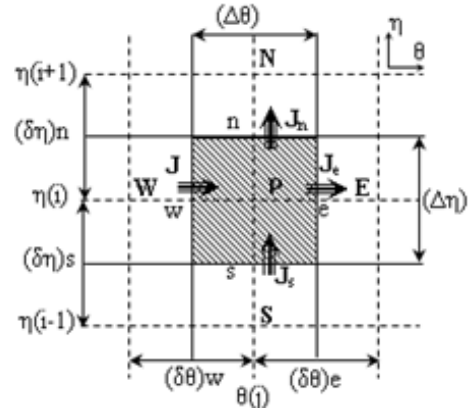


FIG. 3 A typical control volume and its neighbors in a computational domain

2. 2 Discretization of the general transfer equation of a variable ϕ in the control volume:

To illustrate the discretization of the transfer equations by finite volumes method, we consider the transfer equation in its general form:

$$\frac{\partial}{\partial \eta} (H V_{\eta}^{+} \phi - \Gamma_{\phi} \frac{\partial \phi}{\partial \eta}) + \frac{\partial}{\partial \theta} (H V_{\theta}^{+} \phi - \Gamma_{\phi} \frac{\partial \phi}{\partial \theta}) = S \phi \quad (16)$$

Sources and diffusion coefficients are specified in table 1.

Tab. 1 sources and diffusion coefficients of the variables ϕ

ϕ	Γ_ϕ	S_ϕ
T^+	$1/Pr$	0
ω^+	1	$\frac{Gr}{h} \left\{ \begin{array}{l} [F(\eta, \theta)\cos(\alpha) - G(\eta, \theta)\sin(\alpha)] \frac{\partial T^+}{\partial \eta} \\ - [F(\eta, \theta)\sin(\alpha) + G(\eta, \theta)\cos(\alpha)] \frac{\partial T^+}{\partial \theta} \end{array} \right\}$

The discretization equation is obtained by integrating the conservation equations over the control volume shown in Figure 3 Patankar (1980), we obtain the following final form:

$$a_P \phi_P = a_N \phi_N + a_S \phi_S + a_E \phi_E + a_W \phi_W + b \quad (17)$$

The coefficients of equation 17 are well defined by Patankar (1980), the Power Law scheme used to discretize the convective terms in the governing equations.

3. RESULTS AND DISCUSSION

We consider two configurations for our cavity characterized by two values of inclination angle (0° and 45°) and a geometrical form factor ($Fr = 5$) which is defined by:

$$Fr = \frac{\eta_{NI} - \eta_1}{\theta_{NN} - \theta_1}$$

3.1 Grid study:

Several grids were used arbitrarily for the following configuration: ($\alpha=0^\circ$ and $Fr=1$, for $Gr=10^3$, $Gr=10^4$ and $Gr=5.10^4$), to see their effect on the results, table 2 shows us the variation of average Nusselt number and the maximum of the stream function value according to the number of nodes for each grid. We choose the grid (101x111).

Tab. 2 Variation of average Nusselt number and the maximum of the stream-function value according to the number of nodes

$\eta_{NI} \times \theta_{NN}$	Gr = 10^3		Gr = 10^4		Gr = 5.10^4	
	Ψ_{max}	$NU_{moy.}$	Ψ_{max}	$NU_{moy.}$	Ψ_{max}	$NU_{moy.}$
41x51	0.090	1.387	5.582	2.689	16.575	4.268
51x61	0.090	1.387	5.588	2.685	16.572	4.234
61x71	0.109	1.387	5.593	2.682	16.566	4.197
71x81	0.130	1.387	5.596	2.680	15.560	4.197
81x91	0.179	1.387	5.596	2.678	15.555	4.195
91x101	0.201	1.387	5.596	2.678	15.549	4.190
101x111	0.219	1.389	5.596	2.674	15.549	4.190
111x121	0.219	1.389	5.596	2.674	15.549	4.190

3.2 Numerical code validation

Kuehn et al. (1976) have developed a numerical study on natural convection in the annulus between two concentric and horizontal cylinders with a radius was taken equal to 2.6, they calculated a local equivalent thermal conductivity, defined as being the report of a temperature gradient in a convective and conductive heat exchange on a temperature gradient in an exchange conduction:

$$\lambda_{\acute{e}q} = \frac{\frac{\partial T^+}{\partial \eta} \Big|_{convection+conduction}}{\frac{\partial T^+}{\partial \eta} \Big|_{conduction}}$$

They calculated an average value of the conductivity. To validate our numerical code, we compared the average value derived from our calculations with their results. Table 3 illustrates this comparison and we find that quantitatively our results and theirs are in good agreement.

Tab. 3 Comparison of the average thermal conductivity of Kuehn with our results

	Pr	0,70	0,70	0,70	0,70
	Ra	10^2	10^3	6×10^3	10^4
Inner wall	Kuehn	1,000	1,081	1,736	2,010
	Presents calculs	1,000	1,066	1,730	2,068
	E(%)	0,000	1,388	0,346	2,886
Outer wall	Kuehn	1,002	1,084	1,735	2,005
	Presents calculs	1,002	1,066	1,736	2,078
	E(%)	0,000	1,661	0,058	3,641

3.3 Influence of the Grashof number

3.4 Isotherms and streamlines

Figure 4 and figure 5 represent the isotherms and the streamlines for different values of the Grashof number when $\alpha=0^\circ$.

We note that these isotherms and these streamlines are symmetrical about the median fictitious vertical plane. These figures show that the structure of the flow is bi-cellular. The flow turns in the trigonometrically direction in the left side and in opposite direction in the right one (the fluid particles move upwards along the hot wall).

For $Gr=10^2$ the isotherms are almost parallel and concentric curves which coincide well with active walls profiles. In this case the temperature distribution is simply decreasing from the hot wall to the cold wall. The streamlines of the fluid show that the flow is organized in two cells that rotate very slowly in opposite directions.

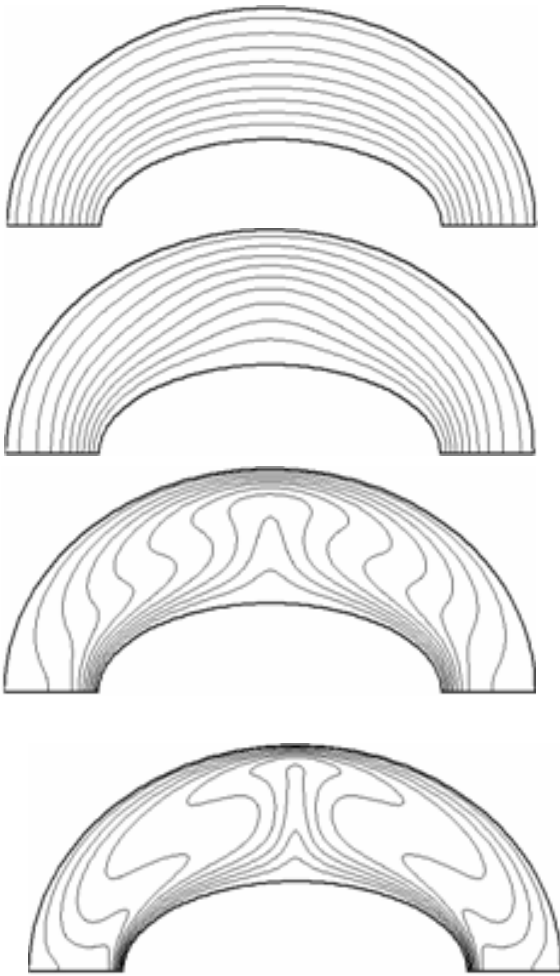


FIG. 4 Isotherms for $\epsilon_1=0.86$, $Fr=5$, $\alpha=0^\circ$ and respectively $Gr=10^2$, $Gr=10^3$, $Gr=10^4$ and $Gr=5.10^4$

We can say that the heat transfer is mainly conductive. The values of the streamline which are given on the corresponding figure are very small.

For $Gr=10^3$ the isothermal lines are transformed symmetrically with respect to the vertical axis and change significantly, and the values of the streamlines mentioned on the same figure, increase also significantly, which translates a transformation of the conductive transfer to the convective transfer, but relatively low as shown in the isotherms shape.

However for $Gr=10^4$ the isotherms are modified and eventually take the form of a mushroom. The temperature distribution decreases from the hot wall to the cold wall. The direction of the deformation of the isotherms is consistent with the direction of rotation of the streamlines. In laminar flow, we can say that under the action of the particles movement taking off from the hot wall at the symmetry axis, the isotherms move away from the wall there. The values of the stream functions increase which means that the convection intensifies.

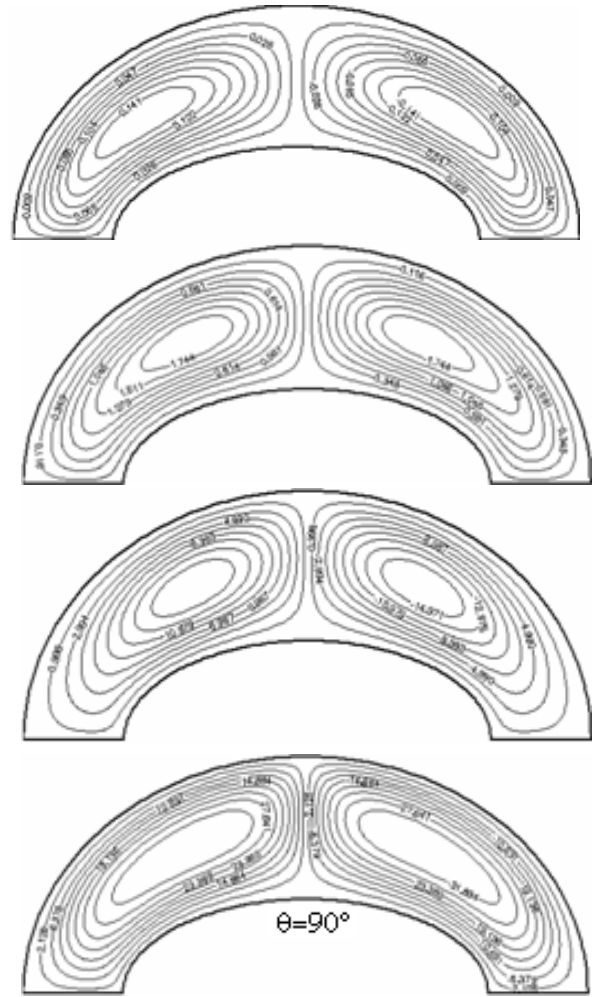


FIG. 5 Streamlines for $\epsilon_1=0.86$, $Fr=5$, $\alpha=0^\circ$ and respectively $Gr=10^2$, $Gr=10^3$, $Gr=10^4$ and $Gr=5.10^4$

The increase of the Grashof number to 5.10^4 intensifies the convection as shown in corresponding figures. Let us note that the isotherms, of all the figures indicated above, were plotted with a $\Delta T^+=0.1$

3.5 Local Nusselt Number

We determine the local Nusselt numbers for which changes along the walls are closely related to the distributions of isotherms and streamlines, so that, qualitatively, these variations and distributions can often be deduced from each other. For example, if we consider a current point on a wall following a coordinated observation of a monotonous reduction in the local Nusselt number corresponds to a directed flow following this coordinate, the observation of an increase corresponds to a directed flow in opposite direction.

3.6 Analogy between the variation of local Nusselt number -isotherms and streamlines

We thus notice on Figure 6, that the variations of local Nusselt number on the inner activate wall are in accordance

with what has just been indicated above, a minimum reflects an existence of two counter-rotating cells pushing away the fluid from the wall, a maximum reflected, on the contrary, the existence of two counter-rotating cells providing the fluid to the wall. What thus enables us to follow the evolution of our flow in our annular space.

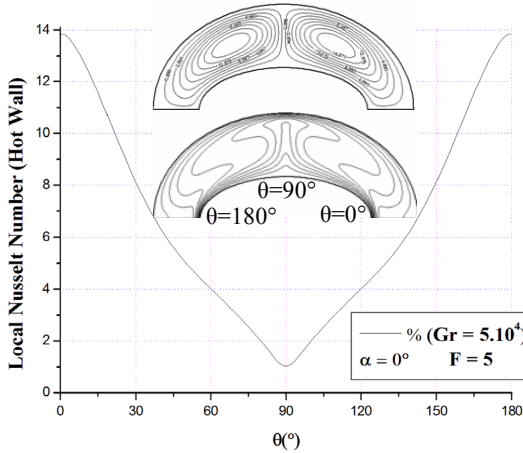


FIG. 6 Variation of local Nusselt number on the inner activate wall

3.7 Variation of local Nusselt number on the hot wall

Figure 7 illustrates the variation of local Nusselt number on the hot wall, and allows us to notice that with the increase of the Grashof number, the value of local Nusselt number on this wall also increases, which is obvious.

3.8 Effect of the angle of inclination α :

We examine here the effect of the inclination of the system compared to the horizontal plane, the angle α is measured from the horizontal plane in the trigonometric direction. We used two values of α (0° and 45°).

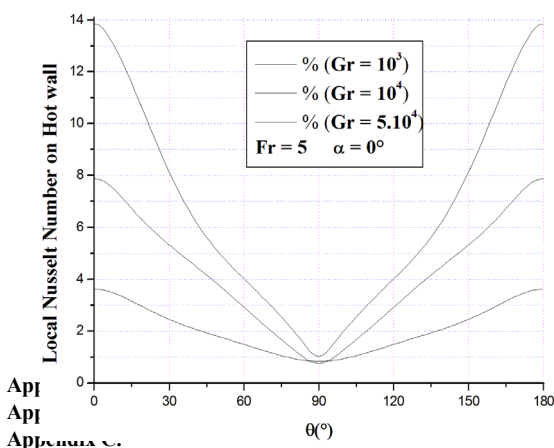


FIG. 7 Variation of local Nusselt number on the hot wall

Appendix D.

3.9 Case where the inclination angle α is zero

In this case, the vertical fictitious median plane is in principle a symmetry plane for transfer phenomena. Therefore by symmetry and in relation to this vertical plane depending on the value of Grashof number, the flow is organized always in two principal cells rotating in opposite directions, as the figures (4-5) show.

3.10 Case where the inclination angle $\alpha = 45^\circ$

When $\alpha=45^\circ$, the symmetry of the system relative to the fictitious vertical plane is destroyed as well illustrated in figure 8 and figure 9, the ends of annular space move upwards for the right part of the system and downwards for the left part. Figure 9 show that the cell of left can more develop that its counterpart on the right part and tends to occupy the entire annular space as the system is inclined more until becoming vertical.

3.11 Local and average Nusselt number

The figure 10 which illustrates the variation of local Nusselt number on the hot wall shows that for $\alpha=0^\circ$ the minimum of local Nusselt number is reached at the angular position $\theta=90^\circ$, which is in agreement with figure 5 which shows that the two cells meet at this precise place while moving away the fluid from this wall. For $\alpha=45^\circ$ the minimum of local Nusselt number moves at the position $\theta=53^\circ$, which is in agreement also with figure 9 which shows that for this inclination, the two cells meet at this angular position while moving away the fluid there from this wall.



FIG. 8 Isotherms for $e_1=0.86$, $Fr=5$, $\alpha=45^\circ$ and $Gr=5.10^4$

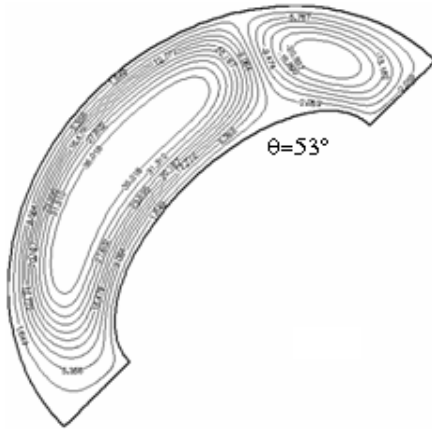


FIG. 9 Streamlines for $e_1=0.86$, $Fr=5$, $\alpha=45^\circ$ and $Gr=5.10^4$

The variation of average Nusselt number on the hot wall as a function of Grashof number illustrated in figure 11 which shows that the inclination α is then without influence when $Gr \leq 10^3$, this translates that the heat transfer is primarily conductive. For the greatest values of the Grashof number, α influences the convective transfer.

CONCLUSION

We established a mathematical model representing the transfer of movement within the fluid and heat through the active walls of the enclosure. This model based on the assumption of Boussinesq and the bidimensionality of the flow. We have developed a calculation code, based on the finite volume method, which determines the thermal and dynamic fields in the fluid and the dimensionless numbers of local and average Nusselt on the active walls of the enclosure, depending to the quantities characterizing the state of the system. The influence of the Grashof number and the inclination of the system, on the flow in stationary mode has been particularly examined.

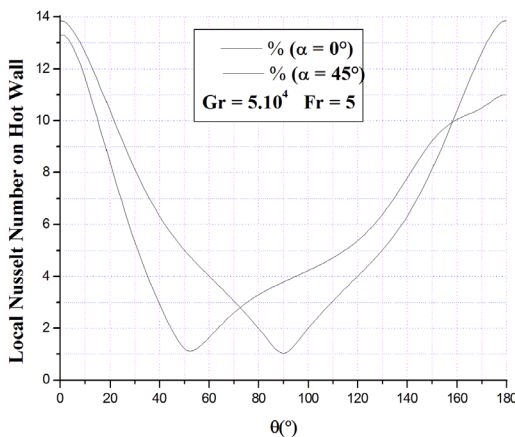


FIG. 10 Variation of local Nusselt number on the hot wall

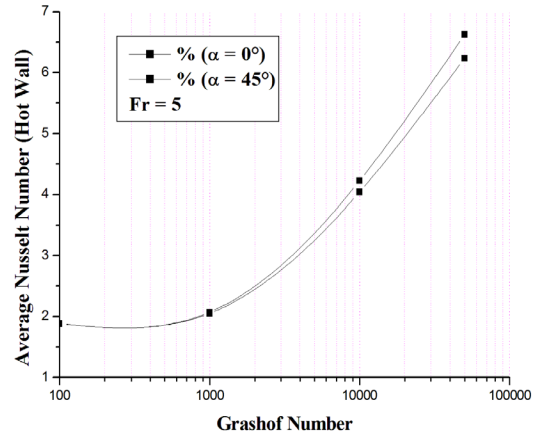


FIG. 11 Variation of the average Nusselt number on the inner activate wall

- Appendix E.
- Appendix F.
- Appendix G.
- Appendix H.
- Appendix I.
- Appendix J.
- Appendix K.
- Appendix L.
- Appendix M.
- Appendix N.
- Appendix O.
- Appendix P.
- Appendix Q.

The results of the numerical simulations have shown that conduction is the regime of heat transfer dominant for Grashof numbers lower than 10^3 . For Grashof numbers higher than 10^3 , the role of the convection becomes dominant, this on the one hand, on the other hand we saw that the transfers are better when our system presents elements of symmetry.

Appendix R.

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